Global Stability of Banking Networks Against Financial Contagion: Measures, Evaluations and Implications

Bhaskar DasGupta

Department of Computer Science University of Illinois at Chicago Chicago, IL 60607 bdasgup@uic.edu

September 16, 2014

• Based on the thesis work of my PhD student Lakshmi Kaligounder

Joint works with Piotr Berman, Lakshmi Kaligounder and Marek Karpinski

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Global Stability of Banking Networks

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Introduction

Global stability of financial system

- Theoretical (computational complexity and algorithmic) results
- Empirical results (with some theoretical justifications)
- Economic policy implications

3 Future research

(a)

Typical functions of financial systems in market-based economy

- borrowing from surplus units
- Iending to deficit units

Financial stability (informally)

ability of financial system perform its key functions even in "stressful" situations

Threats on stability may severely affect the functioning of the entire economy

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study of financial stability - some historical perspectives

research works during "Great Depression" era

- Irving Fisher (1933)
- John Keynes (1936)

Hyman Minsky (1977)

instabilities are inherent (i.e., "systemic") in many capitalist economies



Why financial systems exhibit instability ?

- inherent property of system (i.e., systemic) ?
- caused by "a few" banks that are "too big to fail" ?
- due to government regulation or de-regulation ?
- random event, just happens ?

Examples of conflicting opinions by Economists

- inherent (Minsky, 1977)
- de-regulation of banking and investment laws
 - Yes (Ekelund and Thornton, 2008)
 - No (Calabria, 2009)

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Why study financial instability ?

scientific curiosity

- what is the cause ?
- how can we measure it ?

working of a regulatory agency [Haldane and May, 2011; Berman *et al.*, 2014]

- periodically evaluates network stability
- flags^a network ex ante for further analysis if its evaluation is weak

too many false positives may drain the finite resources of the agency, but vulnerability is too important to be left for an *ex post* analysis

^a Flagging a network as vulnerable does not necessarily imply that such is the case, but that such a network requires further analysis based on other aspects of free market economics that cannot be modeled (e.g., rumors, panic)

1 Introduction

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To investigate financial networks, one must first settle questions of the following type:

- What is the model of the financial network ?
- How exactly failures of individual financial agencies propagate through the network to other agencies ?
- What is an appropriate global stability measure ?

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we extend and formalize an *ex ante* graph-theoretic models for banking networks under idiosyncratic shocks

- originally suggested by (Nier, Yang, Yorulmazer, Alentorn, 2007)
- directed graph with several parameters
- shock refers to loss of external assets
- network can be
 - homogeneous (assets distributed equally among banks)
 - heterogeneous (otherwise)

The model parameters

Details of the model

parameterized node/edge-weighted directed graph $G = (V, E, \Gamma)$

 $\Gamma = \{\mathcal{E}, \mathcal{I}, \gamma\}$

- $\mathcal{E} \in \mathbb{R}$ total external asset
- $\mathcal{I} \in \mathbb{R}$ total inter-bank exposure
- $\gamma \in (0,1)$ ratio of equity to asset

V is set of n banks

$$\sigma_{\nu} \in [0, 1]$$
 weight of node $\nu \in V \left(\sum_{\nu \in V} \sigma_{\nu} = 1 \right)$
share of total external asset for each bank $\nu \in V$

E is set of *m* directed edges (direct inter-bank exposures)

w(e) = w(u, v) > 0 weight of directed edge $e = (u, v) \in E$

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Balance sheet details of a node v



Two banking network models

Two banking network models

Homogeneous model

 $\boldsymbol{\mathcal{E}}$ and $\boldsymbol{\mathcal{I}}$ are equally distributed among the nodes and edges, respectively

 $\sigma_v = 1/|v|$ for every node $v \in V$ $w(e) = \frac{I}{|E|}$ for every edge $e \in E$

Heterogeneous model

 ${\boldsymbol{\mathcal E}}$ and ${\boldsymbol{\mathcal I}}$ are not necessarily equally distributed among the nodes and edges, respectively

$$\sigma_{v} \in (0,1)$$
 & $\sum_{v \in V} \sigma_{v} = 1$

$$w(e) \in \mathbb{R}^+$$
 & $\sum_{e \in E} w(e) = \mathcal{I}$

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How to estimate global stability ?

How to estimate global stability ?

- Via so-called "stress test"
 - give some banks a "shock"
 - see if some of them fail
 - see how these failures lead to failures of other banks



- how does stress ("shock") originate ?
- how does stress ("shock") propagate ?

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How does shock originate ?

Origination of shock (initial bank failures)

Two additional parameters: ${\cal K}$ and Φ

• $0 < \mathcal{K} < 1$

fraction of nodes that receive the shock

• $0 < \Phi < 1$

severity of the shock

i.e., by how much the external assets decrease

One additional notation: Vx

$V_{\mathbf{X}}$ subset of nodes that are shocked

(how Vx is selected will be described later)

(this is the so-called "shocking mechanism")

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How does shock originate ? (continued)

Initiation of shock of magnitude Φ

- for all nodes $v \in V_X$, simultaneously decrease their external assets from e_v by $s_v = \Phi e_v$
 - parameter Φ determines the "severity" of the shock
- if $s_v \leq c_v$, v continues to operate with lower external asset
- if $s_v > c_v$, v dies (i.e., stops functioning) and "propagates" shock

Next ►

meaning of "death" (of a node)how do shocks propagate ?

How do shocks propagate ?

More notations

$$keg^{in}(v) = in-degree of node v$$

 $V_{>e}(V_X) = set of dead nodes$
when initial shock is provided to nodes in V_X



add "(t)" and "(V_X)" to indicate dependence of a variable on t and V_X Examples

$c_{\boldsymbol{v}}(t, V_{\mathbf{X}}) \\ \deg^{\mathrm{in}}(\boldsymbol{v}, t, V_{\mathbf{X}})$:	c_v at time t in-degree of node v at time t	when initial shock
		deg ⁱⁿ changes because dead nodes are removed from the network	is provided to nodes in V _X
$V_{>\!\!<}(t,V_{\mathbf{X}})$		set of dead nodes before time t	J

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How do shocks propagate ?

shock propagation equation

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How do shocks propagate ?

shock propagation equation

Initial shock

Big bang at t = 1: banking "universe" starts

$$V_{>>}(1, V_{X}) = \emptyset$$
 no node is dead before $t = 1$

$$c_{u}(1, V_{\mathbf{X}}) = \begin{cases} c_{u} - s_{u}, & \text{if } u \text{ was shocked } (i.e., \text{ if } u \in V_{\mathbf{X}}) \\ c_{u}, & \text{otherwise} \end{cases} \xrightarrow{\text{net worth of shocked nodes decrease}}$$

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How do shocks propagate ?



Next slide: some intuition behind this equation

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How do shocks propagate ?

intuition behind individual terms of shock propagation equation



Comparison with other attribute propagation models

Some other models for propagation of attributes

influence maximization in social networks

[Kempe, Kleinberg, Tardos, 2003; Chen, 2008; Chen, Wang, Yang, 2009; Borodin, Filmus, Oren, 2010]

disease spreading in urban networks

[Eubank, Guclu, Kumar, Marathe, Srinivasan, Toroczkai, Wang, 2004; Coelho, Cruz, Codeo, 2008; Eubank, 2005]

percolation models in physics and mathematics

[Stauffer, Aharony, Introduction to Percolation Theory, 1994]

the model for shock propagation in banking networks is fundamentally very different from all such models

for detailed comparison, see

P. Berman, B. DasGupta, L. Kaligounder, M. Karpinski, Algorithmica (in press)

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1 Introduction

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Theoretical (computational complexity and algorithmic) results

two measures of global stability

stability index of a network G

 $\begin{array}{l} \mbox{minimum number of nodes that need to be shocked} \\ {\rm SI}^*(G,T) & {\rm so that all nodes in network } G \mbox{ are dead within time } T \\ (\infty \mbox{ if all nodes simply cannot be put to death in any way)} \end{array}$

 $SI^*(G,T) = 0.99 |V|$ stability is good $SI^*(G,T) = 0.01 |V|$ stability is not so good

higher $SI^*(G, T)$ imply better stability

P. Berman, B. DasGupta, L. Kaligounder, M. Karpinski, Algorithmica (in press) 🗇

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Theoretical (computational complexity and algorithmic) results

two measures of global stability

stability index of a network G

minimum number of nodes that need to be shocked SI^{*}(G, T) so that all nodes in network G are dead within time T(∞ if all nodes simply cannot be put to death in any way)

> $SI^*(G,T) = 0.99 |V|$ stability is good $SI^*(G,T) = 0.01 |V|$ stability is not so good

higher $SI^*(G, T)$ imply better stability

dual stability index of a network G

 $\mathsf{DSI}^*(G,T,\mathcal{K})$

maximum number of nodes that can be dead within time *T* if no more than $\mathcal{K}|V|$ nodes are given the initial shock

higher $DSI^*(G, T)$ imply worse stability

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Two types of deaths of network G T=2 violent death!! happens too soon $T=\infty$ slow poisoning, slow but steady

P. Berman, B. DasGupta, L. Kaligounder, M. Karpinski, Algorithmica (in press) -

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Theoretical (computational complexity and algorithmic) results

synopsis of theoretical computational complexity results

 $0 < \varepsilon < 1$ is any constant, $0 < \delta < 1$ is some constant, e is base of natural log

Network type,	Stability SI*(G, T)	Dual Stability $DSI^*(G, T, \mathcal{K})$	
result type	bound, assumption (if any),	bound, assumption (if any)	

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Theoretical (computational complexity and algorithmic) results

synopsis of theoretical computational complexity results

$0 < \varepsilon < 1$ is any constant, $0 < \delta < 1$ is some constant, e is base of natural log

-	Network type,	Stability SI*(G, T)	Dual Stability $DSI^*(G, T, \mathcal{K})$
	result type	bound, assumption (if any),	bound, assumption (if any)
	T = 2	$(1-\varepsilon)\ln n$,	
	approximation hardness	$NP \not\subseteq DTIME(n^{\log \log n})$	
Homo geneous	T = 2, approximation ratio	$O\left(\log\left(rac{ V \Phi \mathcal{E}}{\gamma (\Phi - \gamma) \mathcal{E} - \Phi } ight) ight)$	
	Acyclic, $\forall T > 1$, approximation hardness	APX-hard	$(1 - e^{-1} + \varepsilon)^{-1}, \mathbf{P} \neq \mathbf{NP}$
	In-arborescence,	$O(n^2)$ time, every node fails	$O(n^3)$ time, every node fails
	$\forall T > 1$, exact solution	when shocked	when shocked

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	Network type.	Stability $SI^*(G,T)$	Dual Stability $DSI^*(G, T, K)$
	result type	bound, assumption (if any),	bound, assumption (if any)
	T = 2	$(1-\varepsilon)\ln n$	
- Homo geneous -	approximation hardness	$NP \not\subseteq DTIME(n^{\log \log n})$	
	T = 2, approximation ratio	$O\left(\log\left(\frac{ V \ \Phi \ \mathcal{E}}{\gamma \ (\Phi - \gamma) \ \mathcal{E} - \Phi } ight) ight)$	
	Acyclic, $\forall T > 1$, approximation hardness	APX-hard	$(1 - e^{-1} + \varepsilon)^{-1}, P \neq NP$
	In-arborescence,	$O(n^2)$ time, every node fails	$O(n^3)$ time, every node fails
	$\forall T > 1$, exact solution	when shocked	when shocked
	Acyclic, $\forall T > 1$, approximation hardness	$(1 - \varepsilon) \ln n$, NP $\not\subseteq DTIME(n^{\log \log n})$	$(1 - e^{-1} + \varepsilon)^{-1}$, P \neq NP
Hetero- geneous -	Acyclic, $T = 2$, approximation hardness		n^{δ} , assumption (*) [†]
	Acyclic, $\forall T > 3$, approximation hardness	$2^{\log^{1-\epsilon} n}$, NP $\not\subseteq$ DTIME $(n^{\operatorname{poly}(\log n)})$	
	Acyclic, $T = 2$, approximation ratio [‡]	$O\left(\log \frac{n \overline{\mathcal{E}} \overline{w_{\max}} \overline{w_{\min}} \overline{\sigma_{\max}}}{\Phi \gamma (\Phi - \gamma) \underline{\mathcal{E}} w_{\min} \sigma_{\min} w_{\max}}\right)$	

[†]See our paper for statement of assumption (*), which is weaker than the assumption $P \neq NP$

[‡]See our paper for definitions of some parameters in the approximation ratio

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Theoretical (computational complexity and algorithmic) results

brief discussion of a few proof techniques

Theorem

For homogeneous networks, $SI^*(G,2)$ cannot be approximated in polynomial time within a factor of $(1-\varepsilon) \ln n$ unless NP \subseteq DTIME $(n^{\log \log n})$

reduction from the dominating set problem for graphs

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Theoretical (computational complexity and algorithmic) results



Moreover, in this case, $SI^*(G, any T)$ can be exactly computed in $O(n^2)$ time under some mild assumption

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Theoretical (computational complexity and algorithmic) results



- reformulate the problem to that of computing an optimal solution of a polynomial-size ILP
- use the greedy approach of [Dobson, 1982] for approximation
- careful calculation of the size of the coefficients of the ILP ensures the desired approximation bound

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Theoretical (computational complexity and algorithmic) results

Theorem (homogeneous networks, *n* = number of nodes)

(a) Assuming $P \neq NP$, $DSI^*(G, any T, \mathcal{K})$ cannot be approximated within a factor of $\frac{1}{(1-1/e+\epsilon)}$, for any $\epsilon > 0$, even if G is a DAG^a

(b) If G is a rooted in-arborescence then

$$\mathsf{DSI}^*(G, \mathsf{any}\ T, \mathcal{K}) < \frac{\mathcal{K}}{n} \left(1 + \deg_{\mathrm{in}}^{\mathrm{max}} \left(\frac{\Phi}{\gamma} - 1 \right) \right) \text{ where } \deg_{\mathrm{in}}^{\mathrm{max}} = \max_{\nu \in V} \left\{ \deg^{\mathrm{in}}(\nu) \right\}$$

Moreover, in this case, $\text{DSI}^*(G, \text{any } T, \mathcal{K})$ can be exactly computed in $O(n^3)$ time under some mild assumption

^ae is the base of natural logarithm

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brief discussion of a few proof techniques

Theorem (heterogeneous networks, *n* = number of nodes)

Under a complexity-theoretic assumption for densest sub-hypergraph problem^{*a*}, DSI^{*}(*G*, 2, \mathcal{K}) cannot be approximated within a ratio of $n^{1-\varepsilon}$ even if G is a DAG

^a see B. Applebaum, Pseudorandom Generators with Long Stretch and Low locality from Random Local One-Way Functions, STOC 2012

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Theoretical (computational complexity and algorithmic) results

brief discussion of a few proof techniques

Theorem

For heterogeneous networks, for any constant $0 < \varepsilon < 1$, it is impossible to approximate SI*(G, ______) within a factor of $2^{\log^{1-\varepsilon} n}$ in polynomial time even if G is a DAG unless NP \subseteq DTIME ($n^{\log \log n}$)

reduction is from the MINREP problem

- MINREP : a graph-theoretic abstraction of two-prover multi-round protocol for any problem in NP
- Intuitively, the two provers in MINREP correspond to two nodes that cooperate to kill another specified set of nodes.
- proof is a bit technical
 - culminating to a set of 22 symbolic linear equations between the parameters that we must satisfy

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Global Stability of Banking Networks

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1 Introduction

Global stability of financial system

- Theoretical (computational complexity and algorithmic) results
- Empirical results (with some theoretical justifications)
- Economic policy implications

3 Future research

Empirical results (with some theoretical justifications)

Empirical results (with some theoretical justifications)

shocking mechanism Y: rule to select an initial subset of nodes to be shocked

Idiosyncratic shocking mechanism

[Eboli, 2004; Nier, Yang, Yorulmazer, Alentorn, 2007] [Gai, Kapadia, 2010; May, Arinaminpathy, 2010] [Haldane, May, 2011; Hübsch, Walther, 2012]

select a subset of $\mathcal{K}[V]$ nodes uniformly at random from V

can occur due to operations risks (frauds) or credit risks

Coordinated shocking mechanism

- intuitively, nodes that are • "too big to fail" in terms of their assets are shocked together
- belongs to the general • class of non-random correlated shocking mechanisms

technical details omitted from this talk

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Empirical results (with some theoretical justifications)

Empirical results with some theoretical justifications

Banking network generation

why not use "real" networks ?

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Empirical results (with some theoretical justifications)

Empirical results with some theoretical justifications

Banking network generation

why not use "real" networks ? several obstacles make this desirable goal impossible to achieve, e.g.

- such networks with all relevant parameters are rarely publicly available
- need hundreds of thousands of large networks to have any statistical validity (in our work, we explore more than 700,000 networks)

Empirical results (with some theoretical justifications)

Empirical results with some theoretical justifications

Banking network generation

why not use "real" networks ? several obstacles make this desirable goal impossible to achieve, e.g.

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models for simulated networks

directed scale-free (SF) model

degree distribution of nodes follow a power-law

- defined in [Barábasi, Albert, 1999]
- used by prior researchers such as [Santos, Cont, 2010; Moussa, 2011; Amini, Cont, Minca, 2011; Cont, Moussa, Santos, 2010]
- (in our work) generated using the algorithm outlined in [Bollobas, Borgs, Chayes, Riordan, 2003]

directed Erdös-Rényi (ER) model

 $\forall u, v \in V : \Pr[(u, v) \in E] = p$

- used by prior banking network researchers such as [Sachs, 2010; Gai, Kapadia, 2010; Markose, Giansante, Gatkowski, Shaghaghi, 2009; Corbo, Demange, 2010]
- generation algorithm is straightforward

Empirical results (with some theoretical justifications)

Empirical results with some theoretical justifications

Banking network generation (continued)

we generated directed SF and directed ER networks with average degree 3 and average degree 6

In addition, we used Barábasi-Albert preferential-attachment SF model to generate in-arboescence networks

in-arborescence

- directed rooted tree with all edges oriented towards root
- belong to the class of "sparsest" connected DAG (average degree ≈ 1)
- belong to the class of "hierarchical" networks



Empirical results with some theoretical justifications

Banking network generation (continued)

For heterogeneous networks, we consider two types of inequity of distribution of assets

(0.1,0.95)-heterogeneous

95% of the assets and exposures involve only 10% of banks

a very small minority of banks are significantly larger than the remaining banks

(0.2,0.60)-heterogeneous

60% of the assets and exposures involve only 20% of banks

less extreme situation: a somewhat larger number of moderately large banks

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Empirical results (with some theoretical justifications)

Summary of simulation environment and explored parameter space

parameter	explored values for the parameter	
network type	homogeneous	
	(α,β) -heterogeneous $\alpha = 0.1, \ \beta = 0.95$ $\alpha = 0.2, \ \beta = 0.6$	
network topology	directed scale-free average degree 1 (in-arboresce average degree 3 average degree 6	ice)
	directed Erdös-Rényi average degree 3 average degree 6	number of
shocking mechanism	idiosyncratic, coordinated	combinations
number of nodes	50, 100, 300	> 700,000
ε/1	0.25, 0.5, 0.75, 1, 1.25, 1.5, 1.75, 2, 2.25, 2.5, 2.75, 3, 3.25, 3.5	
Φ	0.5, 0.6, 0.7, 0.8, 0.9	
κ	0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9	
γ	$0.05, 0.1, 0.15, \ldots, \Phi - 0.05$	

To correct statistical biases, for each combination we generated 10 corresponding networks and computed the average value of the stability index over these 10 runs

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Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

Effect of unequal distribution of assets on stability

networks with all nodes having similar external assets display higher stability over similar networks with fewer nodes having disproportionately higher external assets

Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

Effect of unequal distribution of assets on stability

networks with all nodes having similar external assets display higher stability over similar networks with fewer nodes having disproportionately higher external assets

Some theoretical intuition is provided by the following lemma

Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

Effect of unequal distribution of assets on stability

networks with all nodes having similar external assets display higher stability over similar networks with fewer nodes having disproportionately higher external assets

Some theoretical intuition is provided by the following lemma

Lemma

Fix γ , Φ , \mathcal{E} , \mathcal{I} and the graph G. Consider any node $v \in V_X$ and suppose that v fails due to the initial shock. For every edge $(u, v) \in E$, let $\Delta_{\text{homo}}(u)$ and $\Delta_{\text{hetero}}(u)$ be the amount of shock received by node u at time t = 2 if G is homogeneous or heterogeneous, respectively. Then,

 $\mathbb{E}\left[\Delta_{\text{hetero}}(u)\right] \geq \frac{\beta}{\alpha} \mathbb{E}\left[\Delta_{\text{homo}}(u)\right] = \begin{array}{c} 9.5 \mathbb{E}\left[\Delta_{\text{homo}}(u)\right], & \text{if } (\alpha, \beta) = (0.1, 0.95) \\ 3 \mathbb{E}\left[\Delta_{\text{homo}}(u)\right], & \text{if } (\alpha, \beta) = (0.2, 0.6) \end{array}$

This lemma implies that $\mathbb{E}[\Delta_{hetero}(u)]$ is much bigger than $\mathbb{E}[\Delta_{homo}(u)]$, and thus more nodes are likely to fail beyond t > 1leading to a lower stability for heterogeneous networks

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Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

Effect of unequal distribution of assets on "residual instability"

- for homogeneous networks, if the equity to asset ratio γ is close enough to the severity of the shock Φ then the network tends to be perfectly stable, as one would intuitively expect
- however, the above property is *not* true for highly heterogeneous networks in the sense that, even when γ is close to Φ, these networks have a *minimum* amount of instability ("residual instability")

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Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

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- however, the above property is *not* true for highly heterogeneous networks in the sense that, even when γ is close to Φ , these networks have a *minimum* amount of instability ("residual instability")

to summarize

a heterogeneous network, in contrast to its corresponding homogeneous version, has a residual minimum instability even if its equity to asset ratio is very large and close to the severity of the shock

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Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

Effect of external assets on stability

 ϵ/z controls the total (normalized) amount of external investments of all banks in the network

varying the ratio ϵ/z allows us to investigate the role of the magnitude of total external investments on the stability of our banking network



Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

Effect of external assets on stability

 ϵ/r controls the total (normalized) amount of external investments of all banks in the network

varying the ratio $\frac{\varepsilon}{z}$ allows us to investigate the role of the magnitude of total external investments on the stability of our banking network

for heterogeneous banking networks, global stabilities are affected very little by the amount of the total external asset in the system

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Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

Effect of network connectivity (average degree) on stability

prior observations by Economists

- networks with less connectivity are more prone to contagion [Allen and Gale, 2000]
 - rationale: more interbank links may also provide banks with a type of co-insurance against fluctuating liquidity flows

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Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

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- networks with more connectivity are more prone to contagion [Gai and Kapadia, 2008]
 - rationale: more interbank links increases the opportunity for spreading insolvencies to other banks

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Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

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- networks with more connectivity are more prone to contagion [Gai and Kapadia, 2008]
 - rationale: more interbank links increases the opportunity for spreading insolvencies to other banks

Actually, both observations are correct depending on the type of network

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Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

Effect of network connectivity (average degree) on stability

homogeneous network

higher connectivity leads to lower stability

heterogeneous network

higher connectivity leads to higher stability

our paper provides theoretical insights behind these observations

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Global Stability of Banking Networks

Empirical results (with some theoretical justifications)

Conclusions based on empirical evaluations

phase transitions of properties of random structures are often seen

Example (giant component formation in Erdos-Renyi random graphs $\forall u, v \in V$: $\Pr[(u, v) \in E] = p$

 $p \leq (1-\varepsilon)/n \Rightarrow$ with high probability all connected components have size $O(\log n)$

 $p \ge (1+\varepsilon)/n \Rightarrow$ with high probability at least one connected component has size $\Omega(n)$

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Empirical results (with some theoretical justifications)

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phase transition properties of stability

• denser ER and SF networks, for smaller value of K, show a sharp decrease of stability when γ was decreased beyond a particular threshold

 homogeneous in-arborescence networks under coordinated shocks exhibited a sharp increase in stability as ε/x is increased beyond a particular threshold provided γ ≈ Φ/2 our paper provides theoretical insights behind this observation

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Empirical results (with some theoretical justifications)

Software

interactive software FIN-STAB implementing shock propagation algorithm available from www2.cs.uic.edu/~dasgupta/financial-simulator-files



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Global Stability of Banking Networks

1 Introduction

Global stability of financial system

- Theoretical (computational complexity and algorithmic) results
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- Economic policy implications

³ Future research

Economic policy implications

when to flag the financial network for potential vulnerabilities ?

• equity to asset ratios of most banks are low,

or,

 the network has a highly skewed distribution of external assets and inter-bank exposures among its banks and the network is sufficiently sparse,

or,

 the network does not have either a highly skewed distribution of external assets and a highly skewed distribution of inter-bank exposures among its banks, but the network is sufficiently dense

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3 Future research

Future research

Future research questions

Our results are only a first step towards understanding vulnerabilities of banking systems

Further investigate and refine the network model

- network topology and parameter issues
 - network structures that closely resembles "real" banking networks
 - optimal networks structures for a stable financial system

Effect of "diversified" external investments on the stability Other notions of stability

• percentage of the external assets that remains in the system at the end of shock propagation

Questions with policy implications

• identifications of modifications of network topologies or parameters to turn a vulnerable system to a stable one

Thank you for your attention



"But before we move on, allow me to belabor the point even further..."

Questions??



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