

Finish proof that

Lecture 10

TQBF is PSPACE-complete

Last time: Established

$$TQBF \in PSPACE$$

Now: $\forall L \in PSPACE$

$$L \leq_p TQBF.$$

- M_L which decides L

- $\forall x \in \{0,1\}^n$

$M_L(x)$ decides if

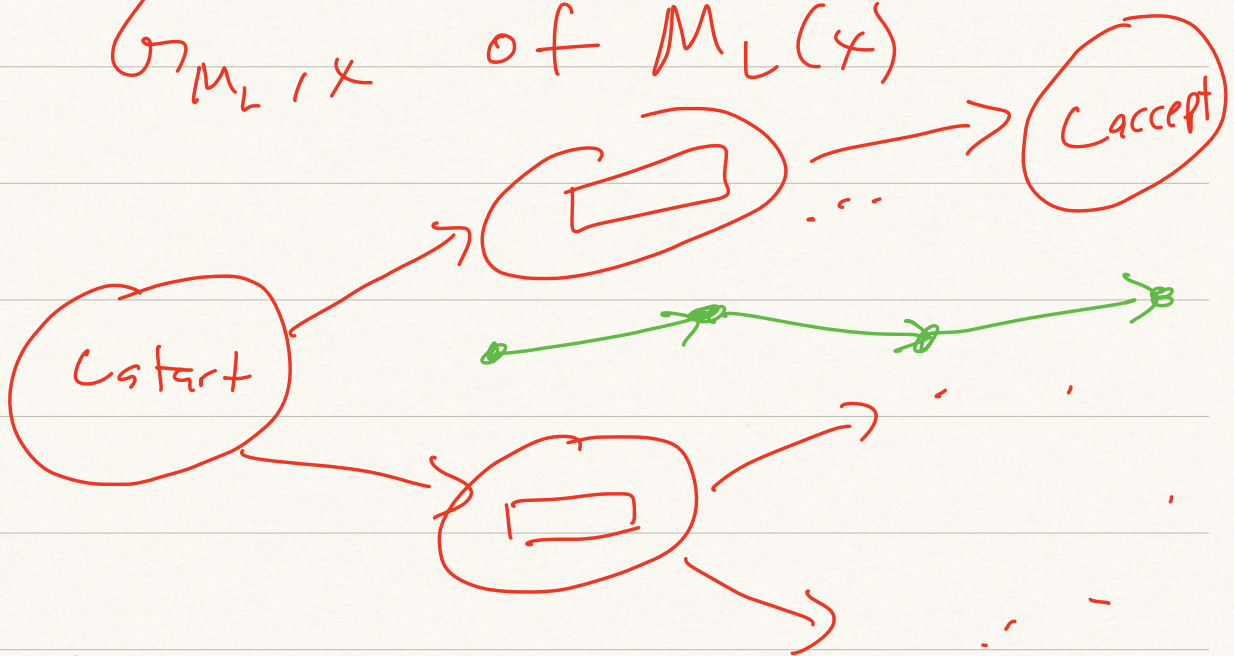
$x \in L$ in space

$$O(\underbrace{s(n)})$$

$c \cdot n$

$$S(n) = n^c \text{ for some } c$$

Given M_L, x , we can
construct config. graph
 $G_{M_L, x}$ of $M_L(x)$



$$(1) M_L(x) = 1 \iff$$

$\exists$ path in $G_{M_L, x}$ from
 C_{start} to C_{accept}

(2) we only need $O(S(n))$
bits to encode any

configuration

③ $\exists$ formula ψ s.t.

$$\psi(c, c') = 1 \iff$$

$\swarrow$
 $O(S(n))$ c, c' are valid configs
and $c \rightarrow c'$ under M 's
transition function
(on input x)

Want: reduction f s.t.

$$x \in L \iff \underbrace{f(x)} \in \text{TQBF}$$

Want to define
a QBF ϕ
s.t.

$$x \in L \iff \underline{\phi} = 1 \Rightarrow \in \text{TCBF}$$

$$M_L(x) = 1 \iff$$

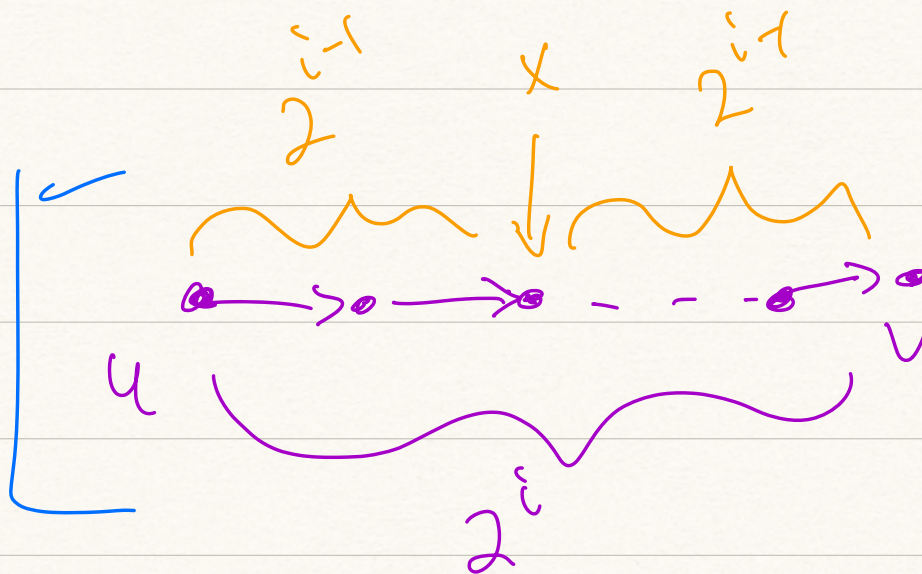
$$\text{Path from}$$

C_{start} to
accept
in $G_{M, x}$

First Attempt

- In any directed G ,
if there is a path
from u to v of
length at most 2^i

Then $\exists$ node x s.t.



path $u \rightarrow x$ of length $\geq 2^{i-1}$
 $x \rightarrow v$ of length $\leq 2^{i-1}$

- We'll build ϕ recursively
- Base Case:

$$\phi_0 = \psi$$

adjacent $\uparrow$ config formula

$$\rightarrow \phi_i(c, c') = 1 \text{ iff}$$

$\exists$ path of length
 $\leq 2^i$ between
configurations c, c'

• $\Phi_k = \Phi$

$k = 2^{O(\log n)} = \# \text{ of nodes in}$

$\downarrow$
 $\Phi(c_{\text{start}}, c_{\text{accept}}) = 1$ $G_{M, X}$

Define



$$\boxed{\phi_i(c, c') = \exists c'' \phi_{i-1}(c, c'') \wedge \phi_{i-1}(c'', c')}$$

$\downarrow O(\text{scan})$

$$\begin{array}{l} \phi_0 \\ \phi_1 \\ \vdots \\ \phi_k \end{array} \quad \begin{array}{l} |\phi_1| \geq 2 \cdot |\phi_0| \\ |\phi_i| \geq 2 \cdot |\phi_{i-1}| \\ \hline k = O(\text{scan}) \\ |\phi_k| \geq 2^{O(\text{scan})} \end{array}$$

X

Insight: Define equivalent QBF to

$$\boxed{\phi_i(c, c') = \exists c'' \phi_{i-1}(c, c'') \wedge \phi_{i-1}(c'', c')}$$

which only increases the size by at most $O(\log n)$ space.

$$\phi_i(L, c') = \boxed{\exists c''} \forall d_1, \forall d_2$$

Path of len. $\leq 2^i$ between L, c' .

$$\left[\begin{array}{l} (d_1 = c \wedge d_2 = c'') \textcircled{1} \checkmark \\ (d_1 = c'' \wedge d_2 = c') \textcircled{2} \leftarrow \end{array} \right]$$

$$\Rightarrow \phi_{i-1}(d_1, d_2)$$

$$\begin{array}{l} \textcircled{1} \phi_{i-1}(L, c'') \checkmark \\ \textcircled{2} \phi_{i-1}(c'', c') \checkmark \\ \textcircled{3} F \Rightarrow \phi_{i-1}(d_1, d_2) \\ \boxed{= T} \end{array}$$

$$\phi_k(L_{\text{start}}, L_{\text{accept}})$$

11
 ϕ

$$|\phi_i| \leq |\phi_{i-1}| + O(s(n))$$

$$\Rightarrow |\phi_{k=O(s(n))}| \leq O(s(n)^2) \checkmark$$

$$|\phi_0| = O(s(n)) \quad \square$$

* we actually showed

TQBF is NPSPACE-
complete

$$\Rightarrow PSPACE = NPSPACE$$

Savitch's Theorem

Fact: $DSPACE(f) \subseteq NSPACE(f)$

Theorem: $\forall$ space constructible s ,
 $NSPACE(s) \subseteq DSPACE(s^2)$

Proof: Let $L \in NSPACE(s)$.
w/ NTM M_L

- Let $G_{M_L, x}$ be the
conf. graph of $M_L(x)$

Fact: # nodes in $G_{M_L, x}$
 $\leq 2^{O(s(n))}$ for $x \in \{0, 1\}^n$

Fact: $M_L(x) = 1 \iff$
 $\exists$ path from c_{start} to
 c_{accept} in $G_{M_L, x}$.

• Goal: Construct DTM
 D_L which decides
 L in space $O(s^2)$

$D_L(x)$:

- simulate $M_L(x)$ by
traversing
 $G_{M_L, x}$

- Run recursive procedure

$$\text{reach}(u, v, i) \\ = 1 \quad \text{iff.}$$

$\exists$ Path from u to v of
length $\leq 2^i$



$\exists z$ s.t.

$$\text{reach}(u, z, i-1) = 1 \\ \text{and } \text{reach}(z, v, i-1) = 1$$

- Run

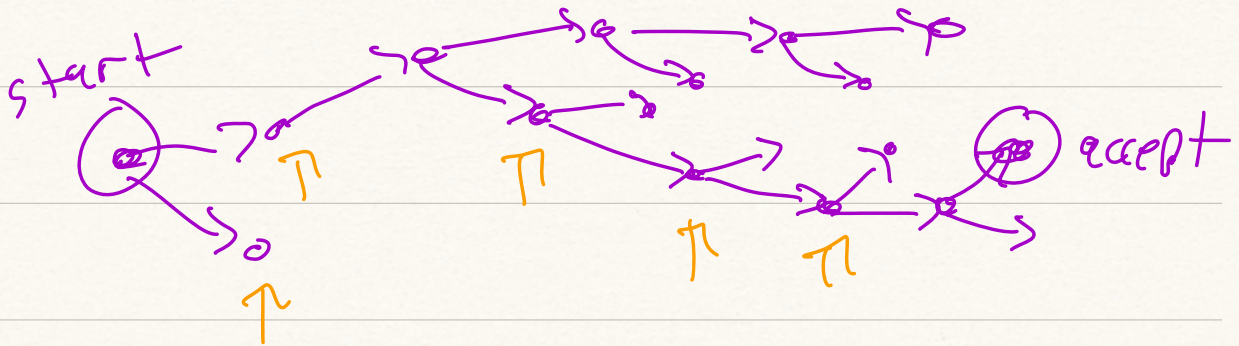
Output $\Rightarrow \text{reach}(c_{\text{start}}, c_{\text{accept}}, \lceil \log(n) \rceil)$

$\hookrightarrow$ Enumerate over all 

$\downarrow$ (nodes) $\hookleftarrow \underline{2^k \text{ nodes}}$

$\hookrightarrow$ check if k space

reach(cstart, d, k-1) = 1
and

$$\text{reach}(d, c_{\text{accept}}, k-1) = 1$$


→ recursion bottoms out after k steps

$\Rightarrow \mathcal{O}(k^2)$ space

$\Rightarrow O(s_{C_n})^2$ space $\square$

$$\begin{array}{ccc}
 & & n^c \\
 & & \downarrow \\
 DSPACE(s) & \subseteq & NSPACE(s) \\
 & & \downarrow \\
 \pi & \subseteq & DSPACE(s^2) \\
 n^c & & n^{2c} \quad \square
 \end{array}$$

NL-Completeness

$NL = \{ L \mid L \text{ is decidable on NTM in at most } O(\log(n)) \text{ space} \}$

Know $PATH \in NL$

$PATH = \{ (G, s, t) : \left. \begin{array}{l} G \text{ is directed} \\ \text{graph w/} \\ \text{path } s \mapsto t \end{array} \right\}$

Unknown $PATH \in L?$

If $PATH \in L$ then

$L = NL$. $\times$

$\rightarrow$ we believe $L \neq NL$

$PATH$ is NL -complete

* We need a new notion
of reducibility

$\forall L, L' \in NL \setminus \{ \emptyset, \{0,1\}^* \}$

$L \leq_p L'$
why?

- Decide on NTM in $O(\log(n))$ space
- Construct $2^{O(\log(n))}$ config. graph in poly-time.

Need: logspace-reducible.

Def: Let $f: \{0,1\}^* \rightarrow \{0,1\}^*$

Then f is (implicitly) logspace computable if $\exists c \geq 1$

s.t. $|f(x)| \leq |x|^c \forall x$
and the languages

$$L_f = \{ (x, i) : f(x)_i = 1 \}$$

$$L'_f = \{ (x, i) : i \leq |f(x)| \}$$

are in L (logspace).

• Def: Let B, C be languages. B is logspace reducible to C , denoted as $B \leq_L C$ if $\exists$ logspace f s.t.

$$x \in B \iff f(x) \in C.$$

• Def. B is NL-complete if

$$(1) B \in NL$$

$$(2) \forall C \in NL \\ C \leq_L B$$

Theorem:

$$(1) A \leq_L B, B \leq_L C, \text{ then } A \leq_L C.$$

$$(2) \text{ IF } A \leq_L B, B \in \mathbf{L}, \text{ then } A \in \mathbf{L}$$

$$\rightarrow \text{ IF } \text{PATH} \in \mathbf{L} \\ \text{then } \mathbf{NL} = \mathbf{L}$$

Theorem PATH is NL-complete.

Proof. PATH $\in$ NL shown before.

For NL-hardness

Show $B \leq_L PATH$.

Let $B \in NL$. Then $\exists$

NTM M_B s.t. $\forall x \in \{0,1\}^n$

$x \in B \iff M_B(x) = 1$ in

$O(\log(n))$ space.

• From $M_B(x)$

↳ construct the config
graph

$\{q_{\text{accept}}, q_{\text{start}}, G_{M_B, x}\} =: f(x)$

$|f(x)| \leq 2^{O(\log(n))}$

$\leq \text{poly}(n) \checkmark$

- In $G_{M_B, x}$, $M_B(x) = 1$

$\hookrightarrow \exists \text{ path from } c_{\text{start}} \rightarrow c_{\text{accept}} \text{ } \Bigg] \text{ PATH}$

- Represent $G_{M_B, x}$ by
a $2^{O(\log(n))} \times 2^{O(\log(n))}$
adjacency matrix

- Entry $(c, c') = 1$ iff
there is an edge
from c to c' in $G_{M_B, x}$

- This is logspace

① Given c, c'

$\exists$ deterministic machine
to check $1A$

C' follows from C
according to M_B 's
transition function.

→ do this in space

$$O(|C| + |C'|)$$

$$= O(\log(n)) \quad \checkmark \quad \square$$