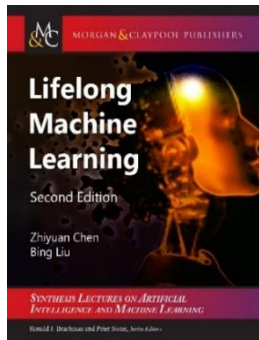

Learning on the Job in the Open World

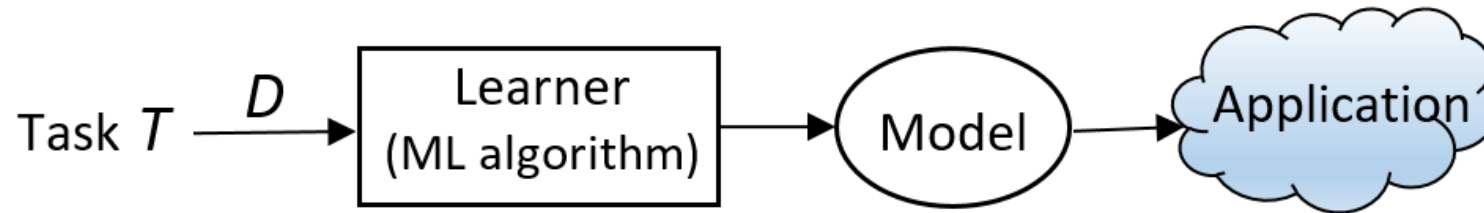


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Introduction

- Classic machine learning: **Isolated single-task learning**



- **Key weaknesses**

- **Closed-world assumption:** nothing new in testing / application
- **Model is fixed during application:** no model revision/improvement in application
- **No knowledge accumulation:** needs a large amount of labeled training data
- Suitable for well-defined tasks in restricted environments
- **This talk: learning during application or on the job.**

Closed-world assumption and open-world

(Fei et al, 2016; Shu et al., 2017)

■ Traditional machine learning:

□ Training data: D^{train} with class labels $Y^{train} = \{l_1, l_2, \dots, l_t\}$.

□ Test data: $D^{test}, Y^{test} \in \{l_1, l_2, \dots, l_t\}$

■ Closed-world: $Y^{test} \subseteq Y^{train}$

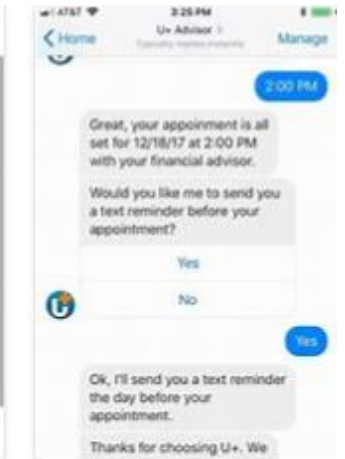
- Classes appeared in testing must have been seen in training, **nothing new**.
- A system that is **unable to identify anything new**, it cannot learn by itself.

■ Open-world: $Y^{test} - Y^{train} \neq \phi$

- There are unseen classes in the test data
 - General case: out-of-distribution data

Chatbots need to learn continuously

- A chatbot's environment is highly **dynamic & open**.
 - What happens if the user says something that the chatbot cannot understand.
 - Hard to train the chatbot by its engineers forever.
 - Chatbot must learn during chatting
 - (learn from other sources)



Self-driving cars need to learn continuously too

- Self-driving cars cannot reach human-level of driving with only rules and off-line training.
 - Impossible to cover all corner cases
 - **Real-world is full of unknowns.**
- Has to learn & adapt continuously in its interaction with humans and the environment by itself.
 - in the **open world** (changes & unknowns).



Chen and Liu. Lifelong machine learning. Morgan & Claypool. 2018

Outline

- Learning on the job continuously
- Detecting novel instances
- Continual learning with knowledge transfer
- Continuous learning in dialogues
- Summary

Old definition of lifelong learning

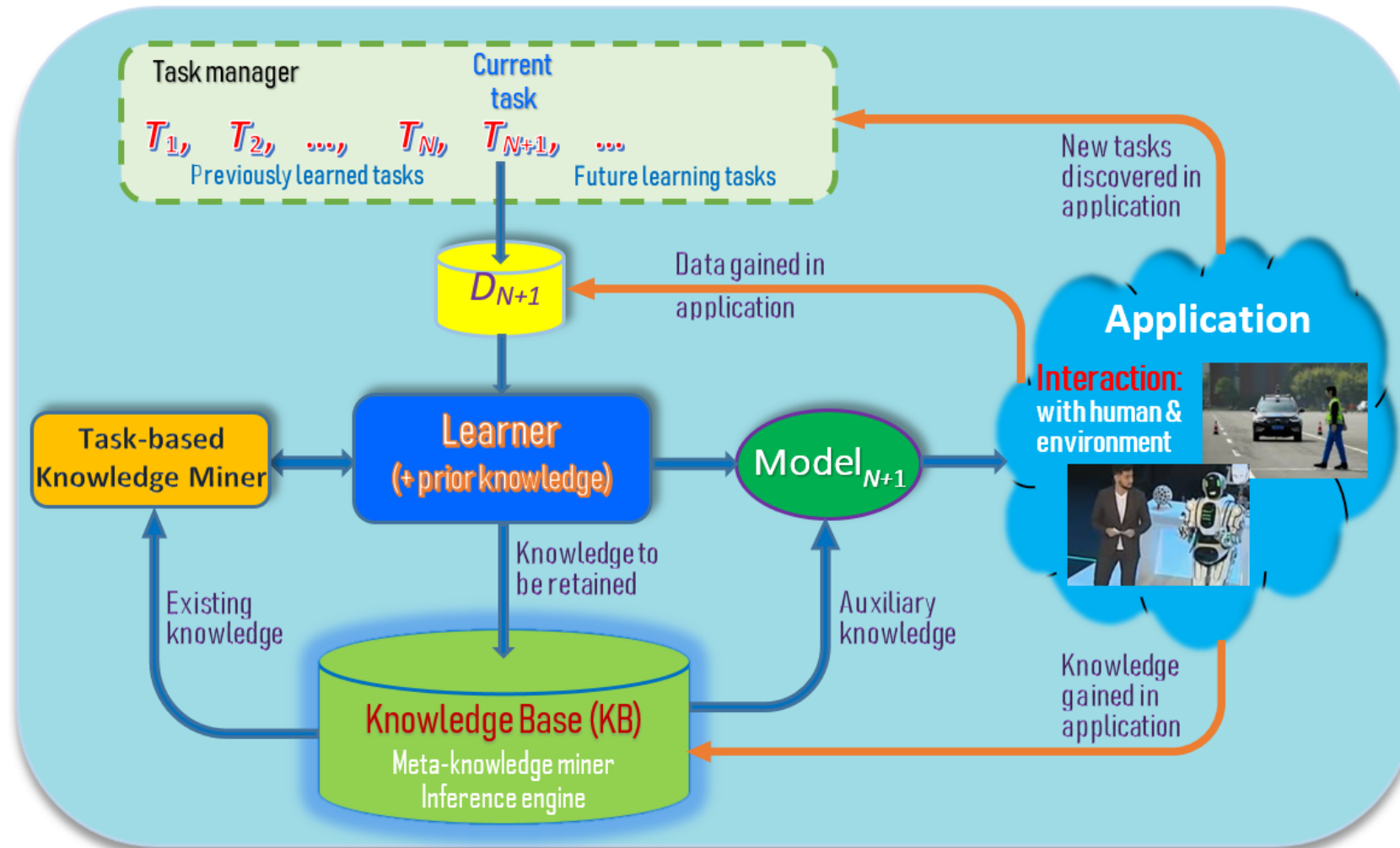
(Thrun 1996, Silver et al 2013; Ruvolo and Eaton, 2013; Chen and Liu, 2014, 2016)

- At any point in time, the learner has learned a sequence of tasks, from 1 to N .
- When faced with the $(N+1)$ th task, it uses the knowledge gained from the N previous tasks to help learn the $(N+1)$ th task.

Thrun. Is learning the n -th thing any easier than learning the first? NIPS, 1996.

Lifelong/continual learning in the open world

(Chen & Liu, 2018, Liu, 2020)



Liu. Learning on the Job: Online Lifelong and Continual Learning. AAI-2020

Key characteristics

(Chen and Liu, 2018-book)

- **Continuous learning process:**
 - *Without forgetting*: Learning a new task should not forget the past.
- **Knowledge accumulation in KB** (long-term memory)
- **Using/adapting past knowledge** to help learn new tasks
- **Learning on the job** during model application **in the open world** in a *self-supervised* manner via *interaction* with humans and the environment.
 - *Discover new tasks and learn them* incrementally/continually.
 - Novel instances of existing/known classes – concept drifting.
 - **Novel/unknown classes or tasks**

Learning on the job

(Liu, 2020, Chen and Liu, 2018)

- It is known in learning science that about **70% of our human knowledge comes from 'on-the-job' learning.**
 - Only about 10% through formal education or training
 - About 70% from on-the-job learning
 - The rest 20% through observation of others
- AI agents should also **learn on the job or during applications**
 - the world is too complex and constantly changing.
 - Impossible to learn everything offline using manually labeled data

(1) Chen and Liu Lifelong machine learning, 2015, 2018. (2) Liu. Learning on the Job: Online Lifelong and Continual Learning. AAIL-2020

Learning on the job in the open-world

(Fei et al, 2016; Shu et al., 2017)

■ Steps:

- **Discover novel instances:** e.g., classify instances in D^{test} to Y^{train} and **detect novel instances** $D^{novel} \subseteq D^{test}$ belonging to L_0 – new tasks
- **Identify the unseen/new classes** in D^{novel} , $L_0 = \{l_{t+1}, l_{t+2}, \dots\}$ and **gather training data**
 - **Interactive self-supervision:** interaction with humans and the environment
- **Continual learning:** Incrementally learn the new classes $\{l_{t+1}, l_{t+2}, \dots\}$ (the new task)

Note: this does not include how the system should respond or react to novelty.

Interactive self-supervision

(Liu, 2020)

- Identify new classes and training data by interacting with
 - **Humans: through natural language**, e.g.,
 - Self-drive cars: asking the passenger
 - What is that object? How do I drive now? Where should I stop?
 - **Chatbots**: learn new knowledge and learn language during chatting.
 - **Environment**: get feedback & use tools (e.g., search engines)
 - Need an internal evaluation system
 - to evaluate environmental feedback
 - **To gather knowledge, and supervisory or reward information.**

Example - a greeting bot in a hotel

(Chen and Liu 2018)

- See an existing/known guest.
 - Bot: “Hello John, how are you today?”
- See a new guest. **Bot must recognize the guest is new/novel.**
 - Bot: “Welcome to our hotel! What is your name, sir?”
 - Guest: “I am David”
 - **Bot learns to recognize David automatically**
 - take pictures of David and incrementally learn to recognize him
- See David next time.
 - Bot: “Hello David, how are you today?”

Outline

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DOC - detecting novel instances (text classification)

(Shu et al. 2017)

- To detect novel instances that do not belong to training classes.

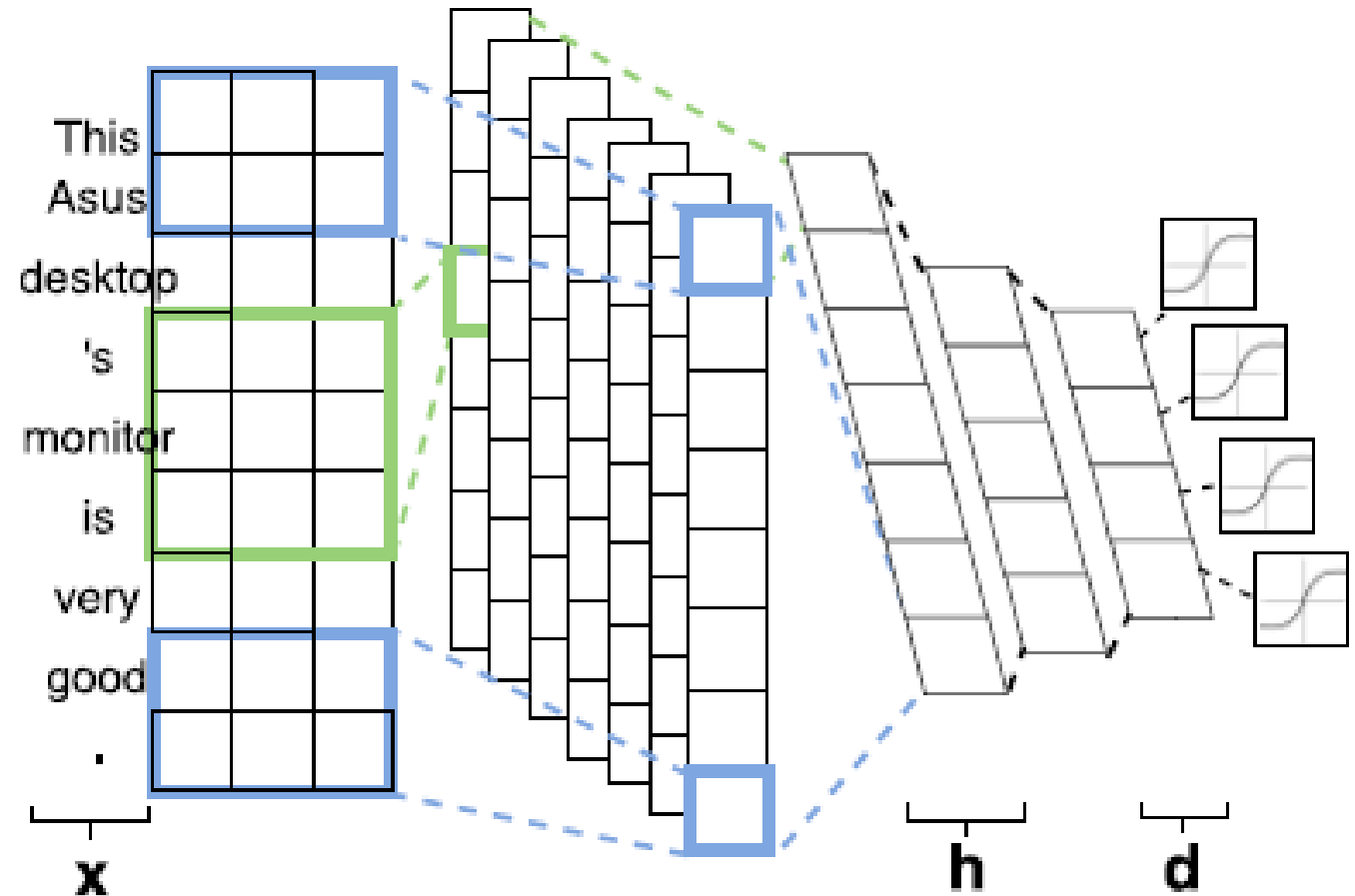


Figure 1: Overall Network of DOC

Shu, Xu, Liu. DOC: Deep Open Classification of Text Documents. EMNLP-2017

Finding the rejection threshold

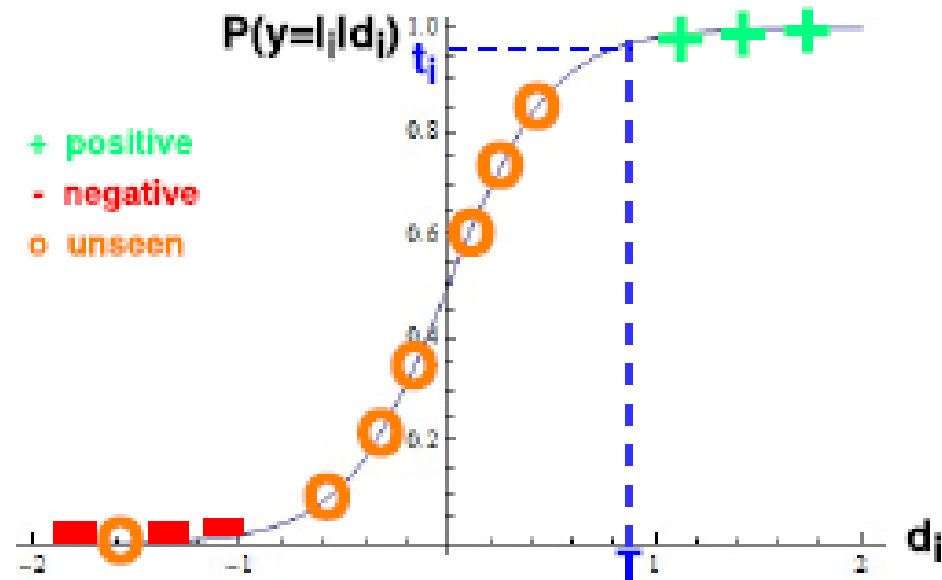
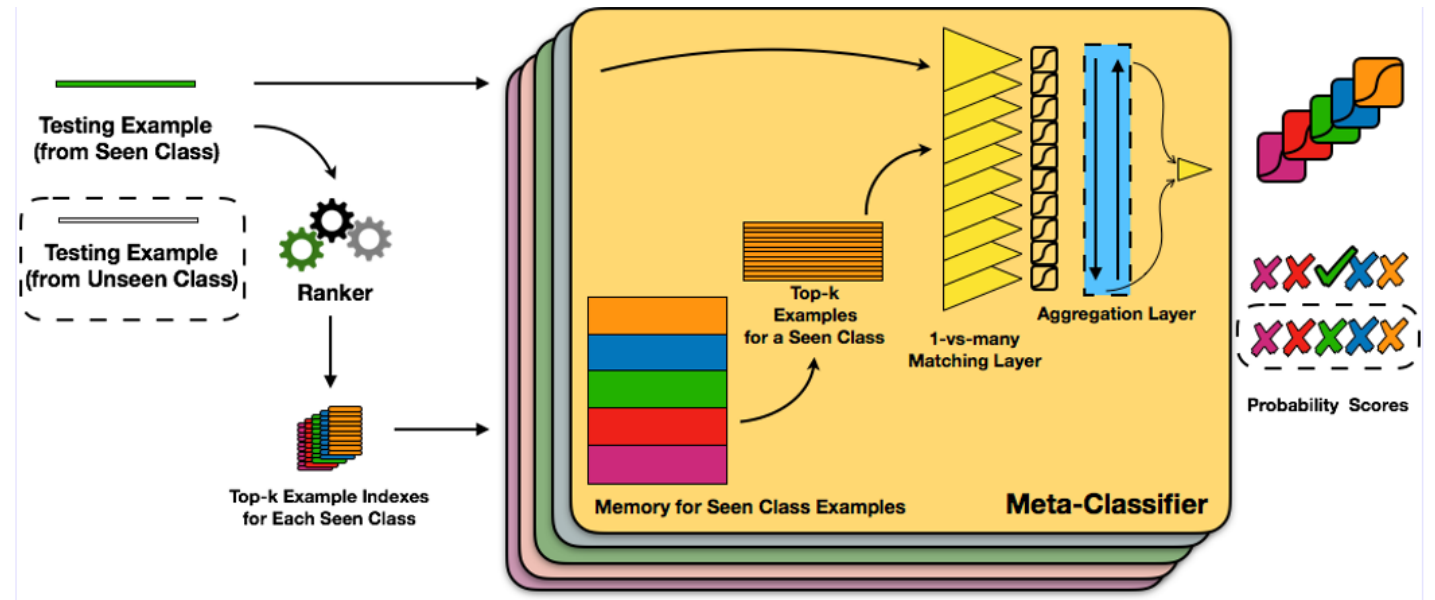


Figure 2: Open space risk of sigmoid function and desired decision boundary $d_i = T$ and probability threshold t_i .

Open-world learning via meta-learning

(Xu et al. 2019)



■ L2AC–meta-learning

- It maintains a dynamic set S of seen classes that allows new classes to be added or deleted without re-training.
 - Each class is represented by a small set of training examples.
- In testing, the meta-classifier uses only the examples of the seen classes on-the-fly for classification and rejection (novel)

Xu, Liu, Shu and Yu. Open-world Learning and Application to Product Classification. WWW-2019

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Continual learning

- **Continual learning (CL)** learns a sequence of tasks.
- **CL has focused** on dealing with *catastrophic forgetting*
 - **Catastrophic forgetting:** In learning a new task, the learner should not forget what it has learned from previous tasks.
 - Extensive research has been done
- **CL should also leverage** the knowledge learned from previous tasks to learn the new task better.

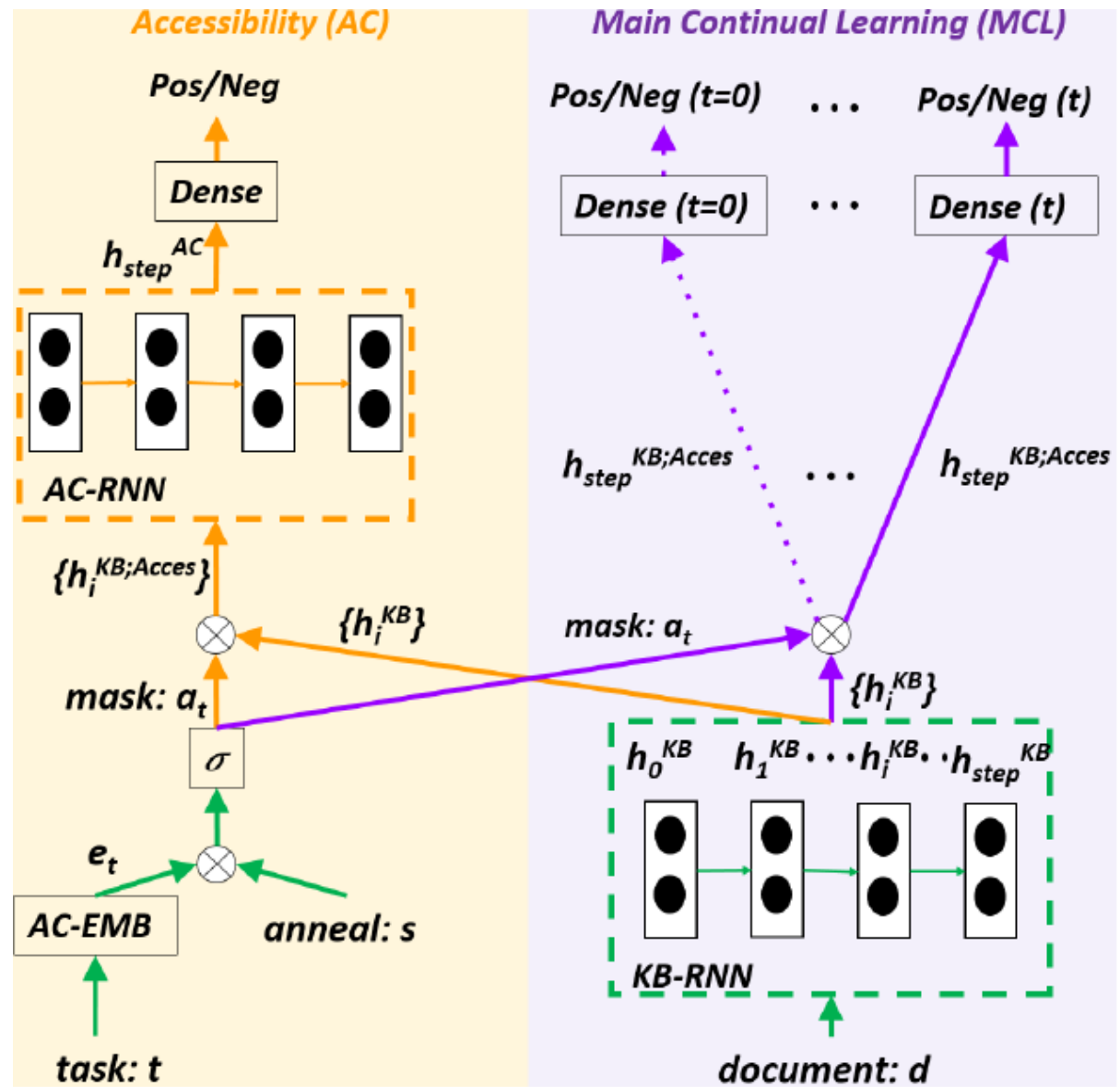
Continual learning with knowledge transfer

(Ke and Liu, 2020)

- Task-based continual learning (TCL)
 - Each task is an independent classification problem.
- **Proposed system:** **KAN** (knowledge accessibility network)
- **Application:** continual sentiment classification
 - **Goal:** learn a sequence of sentiment classification tasks.
 - Each task – classify reviews of a category of products.
 - Review: “*I bought a cellphone a few days ago. It is such a nice phone. The touch screen is really cool. The voice quality is great too.*”
 - Class labels: **positive or negative**

KAN architecture

- Accessibility (AC) module
 - decides accessible units in the KB by the current task t by learning a **binary mask** a_t
- Main continual learning (MCL)
 - **Knowledge base** (KB-RNN).
 - performs the main continual learning and testing.
 - Uses **mask** a_t to **block** not-useful units in KB (avoid forgetting)
 - Useful units **transfer** knowledge.



Experiment results

- 24 sentiment classification tasks & 7 baselines

Average accuracy

Models	All Tasks	Last Tasks
ONE	0.7846	0.7809
LSC	0.8219	0.8246
N-CL	0.8339	0.8477
EWC	0.6899	0.7187
OWM	0.6983	0.7337
HAT	0.6456	0.6938
SRK	0.8282	0.85
KAN	0.8524	0.8799

Effect of forward and backward transfer

Tasks	ONE	N-CL		KAN	
		Forward	Backward	Forward	Backward
First 6 tasks	0.7846	0.7937	0.7990	0.8068	0.8132
First 12 tasks	0.7865	0.8135	0.8199	0.8314	0.8390
First 18 tasks	0.7870	0.8253	0.8327	0.8424	0.8501
First 24 tasks	0.7846	0.8302	0.8339	0.8471	0.8524

Outline

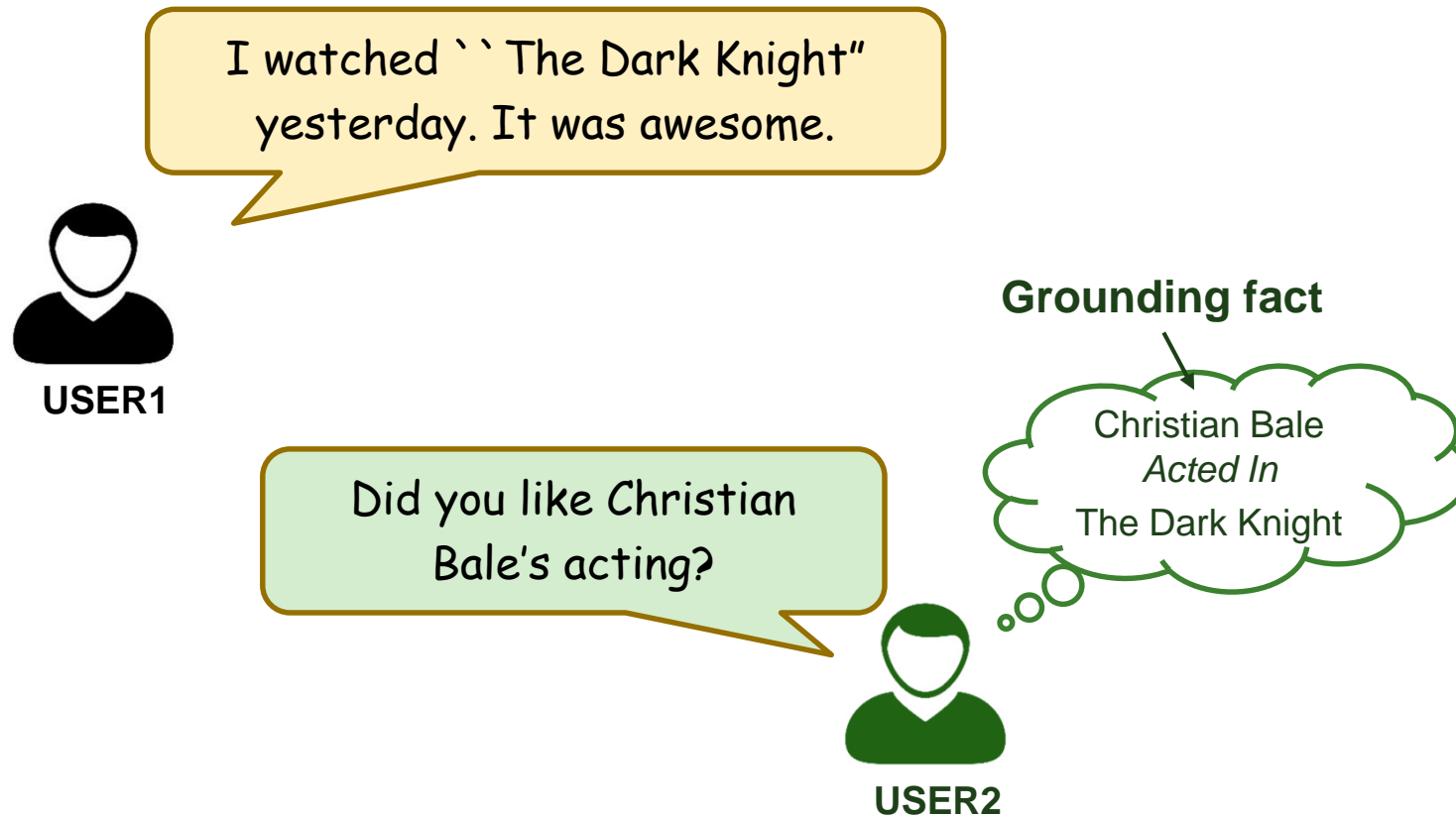
- Learning on the job continuously
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- **Continuous learning in dialogues**
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Continuous knowledge learning in dialogues

(Mazumder et al. 2018, 2019)

- Dialogue systems are increasingly using **knowledge bases (KBs)** storing real-world facts to help generate responses.
 - KBs are inherently incomplete and remain fixed,
 - which limit dialogue systems' conversation capability
- **CILK: *Continuous and Interactive Learning of Knowledge*** for dialogue systems
 - to continuously and interactively learn and infer new knowledge during conversations

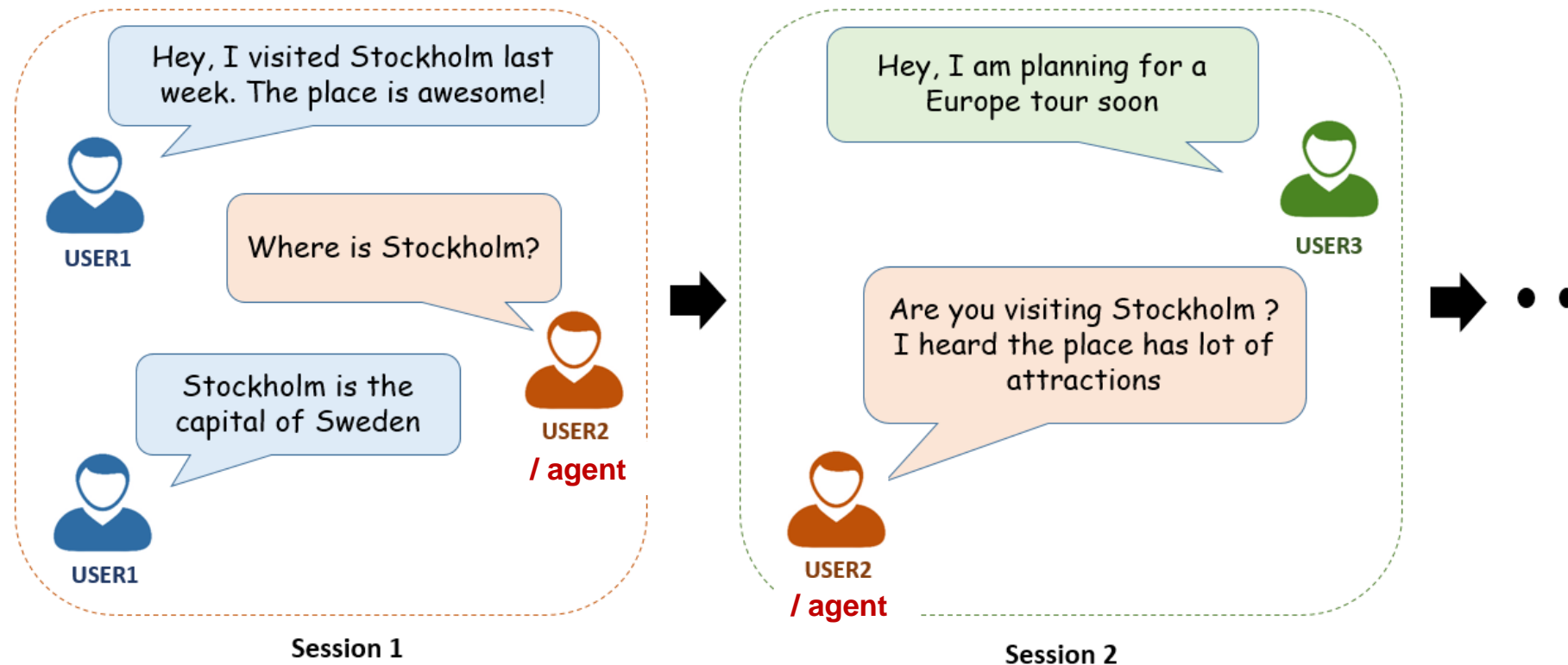
Human conversation is knowledge driven?



Knowledge grounding makes conversation **interesting** and **intelligent**.

Knowledge learning in conversation

Humans Learn and Leverage Knowledge in Lifelong Manner!



Knowledge learning happens in a multi-user environment

Opportunities to learn in conversations

1. Extracting knowledge directly from user utterances. E.g.,
 - **User:** Obama was born in Hawaii.
 - **Agent extracts:** (Obama, BornIn, Hawaii) – expressed in triples **(h, r, t)**
2. Asking user questions & expecting correct answers, e.g.,
 - **Agent:** Where was Obama born?
 - **User:** Hawaii => (Obama, BornIn, Hawaii)
3. **When the agent cannot answer user questions**, it asks the user for some supporting facts and then infers the answers.
 - **We focus on this setting** (which covers 1 and 2)

Problem formulation

- Given a user query / question **(h, r, ?)** [or **(?, r, t)**], our goal is two-fold:
 1. **Answering** the user query or **rejecting** the query to remain unanswered if the correct answer is believed to not exist in the KB
 2. **learning / acquiring** some knowledge (supporting facts) from the user to help the answering task.
- We further distinguish two types of queries:
 - (1) **Closed-world Queries**: h (or t) and r are **known** to the KB
 - (2) **Open-world Queries**: Either one or both h (or t) and r are **unknown**

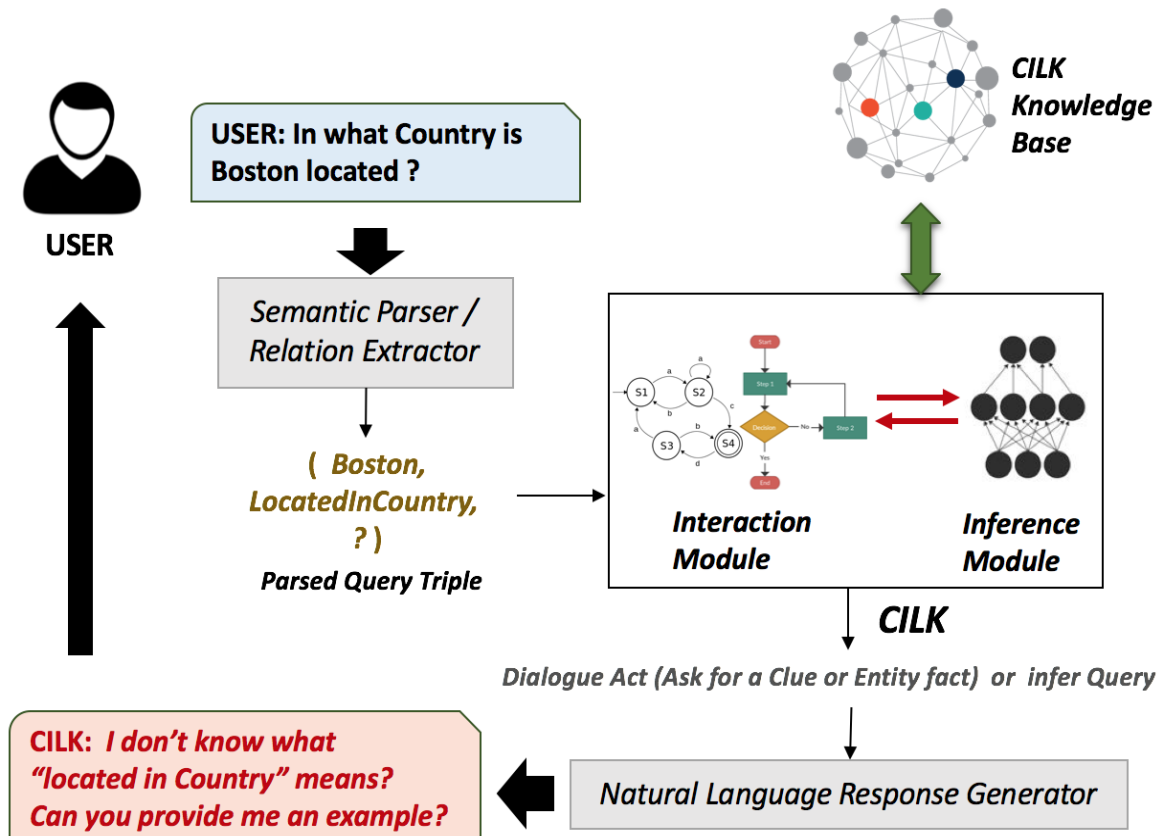


Proposed Soln.

an engine for **Continuous and Interactive Learning of Knowledge (CILK)**

Interactive knowledge learning in dialogue: example

(Mazumder et al. 2019)



USER: (*Boston, LocatedInCountry, ?*) "In what Country is Boston located?" [Query]

CILK: I do not know what "located in Country" means? Can you provide me an example? [Ask for Clue]

USER: (*London, LocatedInCountry, UK*). "London is located in UK." [SF1]

CILK: Got it. Can you tell me a fact about "Boston"? [Ask for Entity Fact]

USER: (*Harvard University, UniversityLocatedIn, Boston*). "Harvard university is located in Boston." [SF2]

CILK: (*Boston, LocatedInCountry, USA*) "Boston is located in USA." [Answer]

Components of the system

- **Knowledge Base** of triples
- **Interaction module**: chatting with the user
 - decides whether to ask or not and formulates questions to ask the user for **supporting facts**
 - Updates KB with the acquired knowledge (used for training)
 - Converts open-world queries to closed-world ones
 - Using support facts to make h (or t) and r known to the KB (added to KB).
- **Inference module**: using the acquired knowledge (**supporting facts**) and KB to answer the resulting closed-world query: (h, r, t).

Natural language interface and grounding

- **Motivation:** when we were testing a self-driving car on the road, it suddenly stopped and refused to move.
 - The road was completely clear and we could not see anything wrong
 - Debugging back in the lab found a small stone on the road.
 - Why cannot the car tell us what the problem was in natural language (NL)?
 - Why cannot we tell the car to go ahead in natural language?
 - Our instruction is a piece of supervisory information.
- To have this capability, the agent needs to continuously learn
 - new natural language expressions that it does not understand, and
 - to ground them to appropriate actions

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Summary

- **Classic ML**: isolated, closed-world, single-task learning
- **AI agents must** learn continuously in the open world, i.e.,
 - Learning on the job (Chen and Liu, 2018; Liu, 2020)
 - Detect new things and learn them with
 - self-motivation & self-supervision
 - *Interactive self-supervision*: need to interact with humans and the environment
 - E.g., self-driving cars and chatbots need such capabilities.
- Current techniques are still in **their infancy**.
 - Novel learning algorithms or paradigm shifts may be needed.

Thank You

Q&A

