

# CS 476 – Programming Language Design

William Mansky

## Questions

Nobody has responded yet.

Hang tight! Responses are coming in.

# Constraint-Based Type Inference

- We can do this in two steps:
  - First, gather all the constraints on type variables
  - Second, find a solution to the constraints
- For step 1, we need constraints for each typing rule:

$$\frac{\Gamma \vdash l_1 : \tau_1 \rightarrow \tau_2 \quad \Gamma \vdash l_2 : \tau_1}{\Gamma \vdash l_1 l_2 : \tau_2} \quad \longrightarrow \quad \frac{\Gamma \vdash l_1 : \tau_1 \quad \Gamma \vdash l_2 : \tau_2}{\Gamma \vdash l_1 l_2 : \tau \mid \{\tau_1 = \tau_2 \rightarrow \tau\}}$$

- $\Gamma \vdash l : \tau \mid S$  means “ $l$  has type  $\tau$  in context  $\Gamma$ , as long as constraints  $S$  are satisfied”

# Unification

- Now we have to *solve* the constraints

let unify (c : constraints) : (ident -> typ option) = ...

- Unification produces a *substitution* of types for type variables

unify  $\{\tau_3 = \text{int}, \tau_4 = \text{int}, \tau_1 = \tau_2 \rightarrow \tau_3, \tau_1 = \text{int} \rightarrow \tau_4\} = \dots$

- Exercise: How would you solve this unification problem? How would you figure out the values of all the type variables?

# Constraint-Based Type Inference

- Now we have to *solve* the constraints

let unify (c : constraints) : (ident -> typ option) = ...

- Unification produces a *substitution* of types for type variables

unify  $\{\tau_3 = \text{int}, \tau_4 = \text{int}, \tau_1 = \tau_2 \rightarrow \tau_3, \tau_1 = \text{int} \rightarrow \tau_4\} =$   
 $\{\tau_3 = \text{int}, \tau_4 = \text{int}, \tau_1 = \text{int} \rightarrow \text{int}, \tau_2 = \text{int}\}$

let type\_of (gamma : context) (e : exp) =  
 let (t, c) = get\_constraints gamma e in  
 let s = unify c in apply\_subst s t

# Unification

- Input: a set of *constraints* of the form  $L = R$ , where  $L$  and  $R$  are types with type variables in them
- Output: a *substitution*, a map from type variables to types (which still may have variables in them)
- The output substitution  $\sigma$  should solve all the constraints: for each  $L = R$  in the input,  $[\sigma]L$  is exactly the same as  $[\sigma]R$

# The Unification Algorithm

- Pick a constraint  $L = R$  from the current set  $S$
- Apply one of the following rules, as appropriate:
  1. Discard
  2. Substitute left
  3. Substitute right
  4. Decompose
- Update the constraint set  $S$  and the substitution  $\sigma$  accordingly
- Repeat on the remaining constraints

# The Unification Algorithm: Discard

- Applies when the constraint is of the form  $T = T$
- Action: remove the constraint from  $S$ , while leaving  $\sigma$  and the rest of  $S$  unchanged

$S: \{\text{int} = \text{int}, \tau_1 = \tau_2, \dots\}$

$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\}$



# The Unification Algorithm: Discard

- Applies when the constraint is of the form  $T = T$
- Action: remove the constraint from  $S$ , while leaving  $\sigma$  and the rest of  $S$  unchanged

$$S: \{\text{int} = \text{int}, \tau_1 = \tau_2, \dots\} \Rightarrow \{\tau_1 = \tau_2, \dots\}$$

$$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\}$$

# The Unification Algorithm: Substitute (L)

- Applies when the constraint is of the form  $x = T$
- Action: add  $\{x \mapsto T\}$  to  $\sigma$ , and apply it to the rest of  $\sigma$  and  $S$

$S: \{\tau_5 = \text{bool}, \tau_1 = \text{int} \rightarrow \tau_5, \dots\}$

$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\}$

# The Unification Algorithm: Substitute (L)

- Applies when the constraint is of the form  $x = T$
- Action: add  $\{x \mapsto T\}$  to  $\sigma$ , and apply it to the rest of  $\sigma$  and  $S$

$S: \{\tau_5 = \text{bool}, \tau_1 = \text{int} \rightarrow \tau_5, \dots\} \Rightarrow \{\tau_1 = \text{int} \rightarrow \text{bool}, \dots\}$

$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\} \Rightarrow \{\tau_5 \mapsto \text{bool}, \tau_4 \mapsto \text{bool} \rightarrow \tau_6, \dots\}$

# The Unification Algorithm: Substitute (L)

- Applies when the constraint is of the form  $x = T$
- Action: add  $\{x \mapsto T\}$  to  $\sigma$ , and apply it to the rest of  $\sigma$  and  $S$

$S: \{\tau_5 = \tau \rightarrow \tau_5, \tau_1 = \text{int} \rightarrow \tau_5, \dots\}$

$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\}$

- “Occurs check”:  $x$  must not be free in  $T$

# The Unification Algorithm: Substitute (L)

- Applies when the constraint is of the form  $x = T$
- Action: add  $\{x \mapsto T\}$  to  $\sigma$ , and apply it to the rest of  $\sigma$  and  $S$

$S: \{\tau_5 = \tau \rightarrow \tau_5, \tau_1 = \text{int} \rightarrow \tau_5, \dots\} \Rightarrow \text{fail}$

$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\}$

- “Occurs check”:  $x$  must not be free in  $T$

# The Unification Algorithm: Substitute (R)

- Applies when the constraint is of the form  $T = x$
- Action: add  $\{x \mapsto T\}$  to  $\sigma$ , and apply it to the rest of  $\sigma$  and  $S$

$S: \{\text{bool} = \tau_5, \tau_1 = \text{int} \rightarrow \tau_5, \dots\} \Rightarrow \{\tau_1 = \text{int} \rightarrow \text{bool}, \dots\}$

$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\} \Rightarrow \{\tau_5 \mapsto \text{bool}, \tau_4 \mapsto \text{bool} \rightarrow \tau_6, \dots\}$

- “Occurs check”:  $x$  must not be free in  $T$

# The Unification Algorithm: Decompose

- Applies when the constraint is of the form

$$T(\tau_1, \dots, \tau_n) = T(v_1, \dots, v_n)$$

- Action: add  $\tau_1 = v_1, \dots, \tau_n = v_n$  to  $S$

$$S: \{ \tau_6 \rightarrow \tau_2 = \tau_5 \rightarrow \text{int}, \tau_1 = \text{int} \rightarrow \tau_5, \dots \}$$

$$\sigma: \{ \tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots \}$$

# The Unification Algorithm: Decompose

- Applies when the constraint is of the form

$$T(\tau_1, \dots, \tau_n) = T(v_1, \dots, v_n)$$

- Action: add  $\tau_1 = v_1, \dots, \tau_n = v_n$  to  $S$

$$S: \{\tau_6 \rightarrow \tau_2 = \tau_5 \rightarrow \text{int}, \tau_1 = \text{int} \rightarrow \tau_5, \dots\} \Rightarrow$$

$$\{\tau_6 = \tau_5, \tau_2 = \text{int}, \tau_1 = \text{int} \rightarrow \tau_5, \dots\}$$

$$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\}$$



# The Unification Algorithm: Decompose

- Applies when the constraint is of the form

$$T(\tau_1, \dots, \tau_n) = T(v_1, \dots, v_n)$$

- Action: add  $\tau_1 = v_1, \dots, \tau_n = v_n$  to  $S$

$$S: \{ \tau_6 \rightarrow \tau_2 = \tau_5 * \text{int}, \tau_1 = \text{int} \rightarrow \tau_5, \dots \}$$

$$\sigma: \{ \tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots \}$$

# The Unification Algorithm: Decompose

- Applies when the constraint is of the form

$$T(\tau_1, \dots, \tau_n) = T(v_1, \dots, v_n)$$

- Action: add  $\tau_1 = v_1, \dots, \tau_n = v_n$  to  $S$

$S: \{\tau_6 \rightarrow \tau_2 = \tau_5 * \text{int}, \tau_1 = \text{int} \rightarrow \tau_5, \dots\} \Rightarrow \text{fail}$

$\sigma: \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \tau_5 \rightarrow \tau_6, \dots\}$

- If the constructors or number of arguments are different, no solution exists

# The Unification Algorithm

- Pick a constraint  $L = R$  from the current set  $S$
- Apply one of the following rules, as appropriate:
  1. Discard
  2. Substitute left
  3. Substitute right
  4. Decompose
- Update the constraint set  $S$  and the substitution  $\sigma$  accordingly
- Repeat on the remaining constraints
- When finished,  $\sigma$  will unify all the original constraints

## Questions

Nobody has responded yet.  
Hang tight! Responses are coming in.

# Constraint-Based Type Inference

- Step 1: gather constraints, outputs pair  $(\tau, S)$  such that if  $S$  can be solved,  $\tau$  is the type of the expression
- Step 2: unify constraints  $S$ , obtain solving substitution  $\sigma$
- Step 3: apply  $\sigma$  to  $\tau$  to get the type of the expression

```
let type_of (gamma : context) (e : exp) =  
  let (t, c) = get_constraints gamma e in  
  let s = unify c in apply_subst s t
```

# Constraint-Based Type Inference: Rules

$$\frac{(n \text{ is an integer literal})}{\Gamma \vdash n : \text{int} \mid \{}}$$

$$\frac{\Gamma(x) = \tau}{\Gamma \vdash x : \tau \mid \{}}$$

$$\frac{\Gamma \vdash l_1 : \tau_1 \mid S_1 \quad \Gamma \vdash l_2 : \tau_2 \mid S_2}{\Gamma \vdash l_1 + l_2 : \text{int} \mid \{\tau_1 = \text{int}, \tau_2 = \text{int}\} \cup S_1 \cup S_2}$$

$$\frac{\Gamma[x \mapsto \tau_1] \vdash l : \tau_2 \mid S \quad \tau_1 \text{ fresh}}{\Gamma \vdash (\text{fun } x \rightarrow l) : \tau_1 \rightarrow \tau_2 \mid S}$$

# The Unification Algorithm

- Pick a constraint  $L = R$  from the current set  $S$
- Apply one of the following rules, as appropriate:
  1. Discard
  2. Substitute left
  3. Substitute right
  4. Decompose
- Update the constraint set  $S$  and the substitution  $\sigma$  accordingly
- Repeat on the remaining constraints
- When finished,  $\sigma$  will unify all the original constraints

# Constraint-Based Type Inference: Example

$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : \tau_1 \rightarrow \tau_2 \rightarrow \text{int} \mid S_1$

$S_1 = \{\tau_3 = \text{int}, \tau_4 = \text{int}, \tau_1 = \tau_2 \rightarrow \tau_3, \tau_1 = \text{int} \rightarrow \tau_4\}$



# Constraint-Based Type Inference: Example

$$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : \tau_1 \rightarrow \tau_2 \rightarrow \text{int} \mid S_1$$
$$S_1 = \{\tau_4 = \text{int}, \tau_1 = \tau_2 \rightarrow \tau_3, \tau_1 = \text{int} \rightarrow \tau_4\}$$
$$\sigma = \{\tau_3 \mapsto \text{int}\}$$

# Constraint-Based Type Inference: Example

$$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : \tau_1 \rightarrow \tau_2 \rightarrow \text{int} \mid S_1$$
$$S_1 = \{\tau_4 = \text{int}, \tau_1 = \tau_2 \rightarrow \text{int}, \tau_1 = \text{int} \rightarrow \tau_4\}$$
$$\sigma = \{\tau_3 \mapsto \text{int}\}$$

# Constraint-Based Type Inference: Example

$$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : \tau_1 \rightarrow \tau_2 \rightarrow \text{int} \mid S_1$$
$$S_1 = \{\tau_1 = \tau_2 \rightarrow \text{int}, \tau_1 = \text{int} \rightarrow \text{int}\}$$
$$\sigma = \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \text{int}\}$$

# Constraint-Based Type Inference: Example

$$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : \tau_1 \rightarrow \tau_2 \rightarrow \text{int} \mid S_1$$
$$S_1 = \{\tau_2 \rightarrow \text{int} = \text{int} \rightarrow \text{int}\}$$
$$\sigma = \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \text{int}, \tau_1 \mapsto \tau_2 \rightarrow \text{int}\}$$

# Constraint-Based Type Inference: Example

$$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : \tau_1 \rightarrow \tau_2 \rightarrow \text{int} \mid S_1$$
$$S_1 = \{\tau_2 = \text{int}, \text{int} = \text{int}\}$$
$$\sigma = \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \text{int}, \tau_1 \mapsto \tau_2 \rightarrow \text{int}\}$$

# Constraint-Based Type Inference: Example

$$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : \tau_1 \rightarrow \tau_2 \rightarrow \text{int} \mid S_1$$
$$S_1 = \{\text{int} = \text{int}\}$$
$$\sigma = \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \text{int}, \tau_1 \mapsto \text{int} \rightarrow \text{int}, \tau_2 \mapsto \text{int}\}$$

# Constraint-Based Type Inference: Example

$$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : \tau_1 \rightarrow \tau_2 \rightarrow \text{int} \mid S_1$$
$$S_1 = \{\}$$
$$\sigma = \{\tau_3 \mapsto \text{int}, \tau_4 \mapsto \text{int}, \tau_1 \mapsto \text{int} \rightarrow \text{int}, \tau_2 \mapsto \text{int}\}$$
$$[\sigma](\tau_1 \rightarrow \tau_2 \rightarrow \text{int}) = (\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int}$$
$$\{\} \vdash (\text{fun } f \rightarrow \text{fun } x \rightarrow f \ x + f \ 3) : (\text{int} \rightarrow \text{int}) \rightarrow \text{int} \rightarrow \text{int}$$

## Questions

Nobody has responded yet.

Hang tight! Responses are coming in.