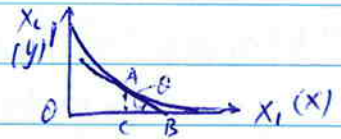


14.2 (a) $x'^2 + y'^2 = 1 - e^{-2t} + e^{-2t} = 1 = \|\dot{\alpha}(t)\|^2 = \|\dot{\alpha}(t)\|$

(b) $-\tan \theta = y'/x' = -e^{-t}/\sqrt{1-e^{-2t}}$. So $\sin \theta = e^{-t}$

$|AB| = y/\sin \theta = e^{-t}/e^{-t} = 1$.

(c) $k = -y'/y = -e^{-t}/e^{-t} = -1$ by Ex 14.20(b) and α being unit speed.



15.1 For $(x_1, x_2, \dots, x_n, 0) \in \mathbb{R}^n$. (Equatorial hyperplane). Solve

$\|t(x_1, \dots, x_n, 0) + (1-t)(0, \dots, 0, -1)\| = 1$, i.e. $\|(tx_1, \dots, tx_n, t-1)\| = 1$

So $t^2(x_1^2 + \dots + x_n^2) + (t-1)^2 = 1$. If $t \neq 0$, then $t = 2(\sum_{i=1}^n x_i^2 + 1)^{-1}$

So $\varphi(x_1, \dots, x_n, 0) = (2x_1, \dots, 2x_n, 1 - \sum_{i=1}^n x_i^2) / (\sum_{i=1}^n x_i^2 + 1)$

15.2 For $(x_1, \dots, x_n, -1)$. Solve $\|(1-t)(0, \dots, 0, 1) + t(x_1, \dots, x_n, -1)\| = 1$, so $t = 4(4 + \sum_{i=1}^n x_i^2)^{-1}$

So $\varphi(x_1, \dots, x_n, -1) = (4x_1, \dots, 4x_n, \sum_{i=1}^n x_i^2 - 4) / (\sum_{i=1}^n x_i^2 + 4)$

15.3 (a) If $v(t) \in f^{-1}(c)$. Let $(\alpha(t), s(t)) = \psi_v^{-1}(v(t))$. So

$f(v(t)) = f(\psi(\alpha(t), s(t))) = s(t) = c$. So $v(t) = \psi(\alpha(t), c) = \varphi_0 \alpha + c \cdot N_0 \alpha$

If $\beta_q(s) = v(t)$, i.e. $\varphi(q) + sN(q) = \varphi(\alpha(t)) + cN(\alpha(t))$. Then since there is a smooth inverse of $\psi|_v$, so $q = \alpha(t)$, $s = c$. Then

$v'(t) \cdot \beta'_q(s) = N(q) \cdot ((\varphi_0 \alpha)'(t) + c \cdot (N_0 \alpha)'(t)) = N(\alpha(t)) \cdot ((\varphi_0 \alpha)'(t) + c \cdot (N_0 \alpha)'(t))$

As $\|N(\alpha(t))\| \equiv 1$ so $N(\alpha(t)) \cdot N_0 \alpha(t) = 0$. By definition, $(N_0 \alpha)'(t) \cdot (\varphi_0 \alpha)'(t) = 0$

So $v'(t) \cdot \beta'_q(s) = 0$. i.e. $f^{-1}(c)$ are everywhere orthogonal to the lines $\beta_q(s)$.

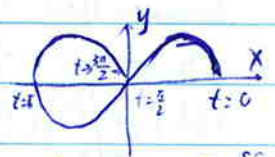
(b) By (a) the vector part of $\nabla f(\psi(q, s)) = \lambda \cdot \beta'_q(s) = \lambda N(q)$.

But $\frac{\partial f}{\partial s} = 1$, i.e. $\nabla f \cdot \frac{\partial \psi}{\partial s} = \nabla f \cdot N(q) = 1$ so $\lambda = 1$ $\nabla f(\beta) = (\beta, N(\beta))$, $\beta = \psi(q, s)$

15.4 $(x(t), y(t)) = (2 \cos t, \sin 2t)$ $t \in (0, \frac{3\pi}{2})$

$(x'(t), y'(t)) = (-2 \sin t, 2 \cos 2t) \neq (0, 0)$ obviously one to one

but when $t \rightarrow \frac{3\pi}{2}$, the curve approaches its own point $(0, 0)$ crossed at $t = \frac{\pi}{2}$, so NOT n-surface



15.5 $\forall (p, v) \in T(S)$. $f(p) = c$, $v \cdot N(p) = 0$. $J = \begin{pmatrix} \nabla f^T & 0 \\ s f_h & N(p) \end{pmatrix} = \nabla f \cdot N(p) \neq 0$.

So $T(S)$ is $2n$ -surface in \mathbb{R}^{2n+2}

15.6 $\forall (p, v) \in T(S)$. $f(p) = c$. $v \cdot N(p) = 0$. $v \cdot v = 0$ $J = \begin{pmatrix} \nabla f^T & 0 \\ \beta & N(p) \\ 0 & 2v \end{pmatrix}$. If $\alpha_1 \begin{pmatrix} \nabla f \\ 0 \end{pmatrix} + \alpha_2 \begin{pmatrix} \beta \\ N(p) \end{pmatrix} + \alpha_3 \begin{pmatrix} 0 \\ 2v \end{pmatrix} = 0$

then $\alpha_1 \nabla f + \alpha_2 \beta = 0 \Rightarrow \alpha_2 = -2v \cdot N(p) = 0 \Rightarrow \alpha_3 = 0$

$\alpha_2 N(p) + \alpha_3 \cdot 2v = 0 \Rightarrow \alpha_1 = 0$ So independent, Thus $T(S)$ is $(2n-1)$ -surface in \mathbb{R}^{2n+2}

15.7 (a) To be in $O(2)$, the matrix $J = \begin{pmatrix} 2x_1 & 2x_2 & 0 & 0 \\ x_3 & x_4 & x_1 & x_2 \\ 0 & 0 & 2x_3 & 2x_4 \end{pmatrix} = (J_1 \ J_2 \ J_3 \ J_4)$ must satisfy:

$$\begin{aligned} x_1^2 + x_2^2 - 1 &= 0 \\ x_1 x_3 + x_2 x_4 &= 0 \\ x_3^2 + x_4^2 - 1 &= 0 \end{aligned}$$

$$Q = (\det(J_1 \ J_2 \ J_3))^2 + (\det(J_1 \ J_3 \ J_4))^2 + (\det(J_2 \ J_3 \ J_4))^2 + (\det(J_1 \ J_2 \ J_4))^2 = 16(x_1 x_4 - x_2 x_3)^2 + \sum_{i=1}^4 x_i^2 = 0 \Rightarrow x_i = 0 \Rightarrow x_1^2 + x_2^2 - 1 \neq 0 \text{ contradiction!}$$

② $x_1 x_4 = x_2 x_3$, so $x_1 x_4 x_3 = x_2 x_3^2$, i.e. $-x_2^2 x_4^2 = x_2 x_3^2$ so $x_2 = 0 \Rightarrow x_1 = \pm 1 \Rightarrow x_4 = 0$
 $\Rightarrow x_3 = \pm 1 \Rightarrow x_1 x_3 = \pm 1$ but $x_2 x_4 = 0 \Rightarrow x_1 x_3 + x_2 x_4 \neq 0$ contradiction

So $Q \neq 0$, $\text{rank}(J) = 3$, $O(2)$ is 1-surface in \mathbb{R}^4

(b) Now $J = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}$ $O(2)_p = \{(a, b, c, d) \mid J \cdot \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} 2a \\ 2b \\ 2c \\ 2d \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}\} = \{(a, b, c, d) \mid a=d=0, b+c=0\}$

Solution 2. Let $\alpha(t) = \begin{pmatrix} \alpha_1(t) \\ \alpha_2(t) \end{pmatrix}$, then $\alpha(t) \in O(2) \Leftrightarrow \|\alpha(t)\| = 1, \alpha_i(t) \cdot \alpha_j(t) = 0$

So $\alpha_i \cdot \alpha_i = 0$ so $(a, b) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0 \Leftrightarrow a=0, (c, d) \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0 \Leftrightarrow d=0$. $\alpha(t_0) = \begin{pmatrix} \alpha_1(t_0) \\ \alpha_2(t_0) \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

$$\alpha_i \cdot \alpha_j + \alpha_i \cdot \alpha_j = 0 \Leftrightarrow (a, b) \begin{pmatrix} 0 \\ 1 \end{pmatrix} + (c, d) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0 \Leftrightarrow b+c=0 \text{ Let } \alpha'(t_0) = \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

$$\text{So } O(2)_p = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid \begin{matrix} a=d=0 \\ b+c=0 \end{matrix} \right\}$$

15.8 (a) Prove that J has rank $\frac{1}{2}n(n+1)$ by induction on n . For $n=2$ 15.7 has proven it.

Let the matrix be written as $\begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix}$, the constraints are $\|\alpha_i\|^2 = 1, \alpha_i \cdot \alpha_j = 0^{i \neq j}$. So Jacobian is

$$\text{rank } J_n = \text{rank} \begin{pmatrix} 2\alpha_1 & & & \\ & 2\alpha_2 & & \\ & & \ddots & \\ & & & 2\alpha_n \end{pmatrix} = \text{rank} \begin{pmatrix} J_{n-1} & 0 \\ \alpha_n & 2\alpha_n \end{pmatrix} = \text{rank} \begin{pmatrix} J_{n-1} & 0 \\ \alpha_n & 2\alpha_n \end{pmatrix}$$

Note the lowest n rows are linearly independent. As $\exists \beta_1 \dots \beta_n \in \mathbb{R}$ s.t.

$$\beta_n \begin{pmatrix} 0 \\ \vdots \\ \alpha_n^T \end{pmatrix} + \beta_{n-1} \begin{pmatrix} \alpha_{n-1}^T \\ 0 \end{pmatrix} + \beta_{n-2} \begin{pmatrix} \alpha_{n-2}^T \\ 0 \\ 0 \end{pmatrix} + \dots + \beta_1 \begin{pmatrix} \alpha_1^T \\ 0 \\ \vdots \\ 0 \end{pmatrix} = 0 \text{ So } \beta_i \alpha_i^T = 0 \text{ } i=1 \dots n-1$$

$$\sum_{i=1}^n \beta_i \alpha_i^T = 0$$

As none of the α_i is straight 0, $\beta_i = 0$ for $i=1 \dots n-1$ by ①. Then by ② $\beta_n \alpha_n^T = 0$ so $\beta_n = 0$.

Finally the rows in $(J_{n-1} \ 0)$ (the first $\frac{n(n-1)}{2}$ rows) are independent of the last n rows, because these $\frac{n(n-1)}{2}$ rows all have last n elements straight 0 and none of α_i is straight 0. So $\text{rank } J_n = n + \text{rank } J_{n-1} = n + \frac{n(n-1)}{2} = \frac{n(n+1)}{2}$. So $O(n)$ is $\frac{n(n-1)}{2}$ surface in \mathbb{R}^{n^2}

(b) Let $\beta = \begin{pmatrix} \beta_1 \\ \vdots \\ \beta_n \end{pmatrix} \in O(n)_p$ then $J\beta = 0$, i.e. $\left\{ \begin{matrix} \alpha_i \cdot \beta_i = 0 \Rightarrow \beta_{ii} = 0 \\ \alpha_i \cdot \beta_j + \alpha_j \cdot \beta_i = 0 \Rightarrow \beta_{ij} + \beta_{ji} = 0 \end{matrix} \right\} \Rightarrow O(n)_p = \left\{ P \in \mathbb{R}^{n \times n} \mid \begin{matrix} P_{ij} + P_{ji} = 0 \end{matrix} \right\}$

If we use the hint in Ex 15.7(b). $\alpha(t) \in O(n), \|\alpha(t)\| = 1, \alpha_i(t) \cdot \alpha_j(t) = 0$ This is because if $\sum \beta_i \alpha_i = 0$ then $0 = \alpha_i \cdot \sum \beta_j \alpha_j = \beta_i \alpha_i \cdot \alpha_i = \beta_i$

So $\alpha_i(t) \cdot \alpha_i(t) = 0, \alpha_i(t) \cdot \alpha_j(t) + \alpha_j(t) \cdot \alpha_i(t) = 0$
 i^{th} element of $\alpha_i(t) = 0, i^{\text{th}}$ element of $\alpha_j(t) + j^{\text{th}}$ element of $\alpha_i(t) = 0$
 which yields the same result/conclusion

15.9 $\forall v \in \mathbb{R}^n \setminus \{0\} \exists v \in \mathbb{R}^n \mid \nabla f_i(p) \cdot v = 0 \Leftrightarrow \nabla f_i(p) \cdot v = 0 \forall i \Leftrightarrow v \in \text{Ker } df_p$

15.10 (brief proof). Since $J = \begin{pmatrix} \nabla f_1 \\ \vdots \\ \nabla f_k \end{pmatrix}$ is fully ranked, so there are k independent columns indexed by i_1, \dots, i_k , which form matrix P . Define $\psi(x_1, \dots, x_n)$ as $\psi(x_1, \dots, x_n) = \psi(x_1, \dots, x_{i_1-1}, f_1(x_1, \dots, x_{i_1}), x_{i_1+1}, \dots, x_{i_k-1}, f_k(x_1, \dots, x_n), x_{i_k+1}, \dots, x_{n+1})$, whose Jacobian J satisfies $\det(J) = \det(P) \neq 0$. Then go on as in proof of Thm 1 by applying inverse function theorem. Finally, $U = \{(u_1, \dots, u_n) \in \mathbb{R}^n \mid a_j < u_j < b_j \text{ for } j < i_1, a_{j+1} < u_j < b_{j+1} \text{ for } j \in \{i_1, i_2, \dots, i_k\}, a_{j+k} < u_j < b_{j+k} \text{ for } j \in \{i_k, i_{k-1}, \dots, i_1\}\}$ and define $\varphi: U \rightarrow \mathbb{R}^{n+k}$ by $\varphi(u_1, \dots, u_n) = (\psi|_U)^{-1}(u_1, \dots, u_{i_1-1}, c_1, u_{i_1+1}, \dots, u_{i_k-1}, c_k, u_{i_k+1}, \dots, u_n)$. (elsewhere, just change $n+1$ to $n+k$ in proof of Thm 1)

15.11 (brief proof). Define $U \times \mathbb{R}^k \rightarrow \mathbb{R}^{n+k}$ by $\psi(q, t_1, \dots, t_k) = \psi(q) + \sum_{i=1}^k t_i N_i(q)$, where N_i are the vector fields along ψ which span the normal space $(\text{Image } d\psi_q)^\perp$ for each $q \in U$. Then Jacobian $J_\psi(p, 0, \dots, 0) = (J_\psi(p), N_1(p), \dots, N_k(p))$ whose determinant $\neq 0$. By the inverse func thm, there is an open set $V \subset U \times \mathbb{R}^k$ about $(p, 0, \dots, 0)$ such that the restriction $\psi|_V$ of ψ to V maps V one to one into the open set $\psi(V)$, and $(\psi|_V)^{-1}$ is smooth. By shrinking V if necessary, we may assume $V = U_1 \times I^k$ for some open set $U_1 \subset U$ containing p and some interval $I \subset \mathbb{R}$ containing 0 . Now define $f: \text{Image } \psi|_V \rightarrow \mathbb{R}^k$ by $f(\psi(q, t_1, \dots, t_k)) = (t_1, \dots, t_k)$. f is well defined and is smooth because f is the composition of the smooth map $(\psi|_V)^{-1}$ and projection map $U_1 \times I^k \rightarrow I^k$. The level set $f^{-1}(0, \dots, 0)$ is just $\psi(U_1)$, because $f^{-1}(0) = \{\psi(q, t_1, \dots, t_k) \mid q \in U_1, t_i = 0\} = \{\psi(q) \mid q \in U_1\}$. Finally we prove that $Jf(\beta)$ is fully ranked for $\beta = \psi(q, 0, \dots, 0) \in f^{-1}(0, \dots, 0)$. Let $\alpha_i(s) = \psi(q) + s \cdot N_i(q)$ then $\nabla f_j(\beta) \cdot N_i(q) = \nabla f_j(\alpha_i(0)) \cdot \dot{\alpha}_i(0) = \frac{d}{ds} (f_j \circ \alpha_i)(0) = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$. So $\begin{pmatrix} \nabla f_1(\beta) \\ \vdots \\ \nabla f_k(\beta) \end{pmatrix} \cdot \begin{pmatrix} N_1(q) \\ \vdots \\ N_k(q) \end{pmatrix} = I_k$. By definition $\text{rank}(N_1(q), \dots, N_k(q)) = k$. To be fast, let's quote a matrix result: $\text{rank}(AB) \leq \min(\text{rank}(A), \text{rank}(B))$. Now $k \leq \min(\text{rank}(A), \text{rank}(B))$. But both $\text{rank}(A)$ and $\text{rank}(B) \leq k$ thus $\text{rank}(A) = \text{rank}(B) = k$, i.e., A is fully ranked. To prove $\text{rank } Jf(\beta) = k$, another way is: assume $\sum_{i=1}^k \beta_i \nabla f_i(\beta) = 0$, then $\sum_{i=1}^k \beta_i (\nabla f_i(\beta) \cdot B) = 0$. But $\nabla f_i(\beta) \cdot B$ is just the i^{th} row of I_k . So $\beta_i = 0$ for all $i=1, \dots, k$, i.e. $\{\nabla f_1(\beta), \dots, \nabla f_k(\beta)\}$ are independent. Thus $\psi(U_1) = f^{-1}(0, \dots, 0)$ is an n -surface in \mathbb{R}^{n+k} .

15.12

15.12(a) $\varphi(p+tv) = (2(x_1+tv_1), \dots, 2(x_n+tv_n), \sum_{j=1}^n (x_j+tv_j)^2 - 1) / (1 + \sum_{j=1}^n (x_j+tv_j)^2)$
 $\frac{d}{dt} \Big|_0 \varphi(p+tv) = (2v_i (\sum_{j=1}^n x_j^2 + 1) - 4x_i \sum_{j=1}^n x_j v_j \text{ for } i=1, \dots, n, -4 \sum_{j=1}^n x_j v_j) / (\sum_{j=1}^n x_j^2 + 1)^2$
 So $\|d\varphi(v)\|^2 = \|\frac{d}{dt} \Big|_0 \varphi(p+tv)\|^2 = 4 \left\{ \sum_{j=1}^n [v_j (\sum_{j=1}^n x_j^2 + 1) - 2x_j \sum_{j=1}^n x_j v_j]^2 + 4 (\sum_{j=1}^n x_j v_j)^2 \right\} / (\sum_{j=1}^n x_j^2 + 1)^4$
 $= 4 (\sum_{j=1}^n x_j^2 + 1)^{-2} \|v\|^2$ So $\lambda(p) = \frac{2}{\|p\|^2 + 1}$

(b) $d\varphi(v) \cdot d\varphi(w) = \frac{1}{4} (\|d\varphi(v) + d\varphi(w)\|^2 - \|d\varphi(v) - d\varphi(w)\|^2)$ then by linearity of $d\varphi_p$

$$= \frac{1}{4} (\|d\varphi(v+w)\|^2 - \|d\varphi(v-w)\|^2) = \frac{1}{4} \lambda^2(p) (\|v+w\|^2 - \|v-w\|^2) = \lambda^2(p) \cdot v \cdot w.$$

15.13 Let $\tilde{S} = \{q \in S \mid q \text{ can be joined to } p \text{ by a continuous curve in } S\}$. Let $S = f^{-1}(c)$. First \tilde{S} is obviously connected. $\forall q_1, q_2 \in \tilde{S}$, just concatenate their curve joining p will yield a continuous curve between q_1 and q_2 . Since $\tilde{S} \subseteq S$, so $\forall q \in \tilde{S}$. $\nabla f(q) \neq 0$. Now we only need to prove that ~~there~~ ^{there} is an open set ~~is a~~ U , s.t. $\tilde{S} = \{x \in U \mid f(x) = c\}$. $\tilde{S} = \{x \in U \mid f(x) = c\}$. We mimic the proof of Thm 3

For each $q \in \tilde{S} \subseteq S$, let $\varphi_q: U_q \rightarrow S$ be a local parametrization of S whose image contains q and let $\psi_q: U_q \times \mathbb{R} \rightarrow \mathbb{R}^{n+1}$ be defined by $\psi_q(r, s) = \varphi_q(r) + sN(\varphi_q(r))$, where N is the orientation of S . Then as in the proof of Thm 2, we can find an open set V_q about $(\varphi_q^{-1}(q), 0)$ in $U_q \times \mathbb{R}$ s.t. $\psi_q|_{V_q}$ maps V_q one to one onto an open set U'_q in \mathbb{R}^{n+1} , and $(\psi_q|_{V_q})^{-1}: U'_q \rightarrow V_q$ is smooth. Furthermore by shrinking V_q if necessary, we may assume that $\psi_q(r, s) \in S$ for $(r, s) \in V_q$ iff $s = 0$. Since V_q is an open set, then for any $u \in U'_q \cap S$, ~~there must be a unique~~ ^{let $(\psi_q|_{V_q})^{-1}(u) = (r, 0)$ must be 0} $u \in U'_q \cap S$, ~~there must be a unique~~ $u \in U'_q \cap S$. Since U'_q is open and connected, there is a smooth curve $\alpha(t): [a, b] \rightarrow U'_q$ s.t. $\alpha(a) = \psi_q^{-1}(q)$ and $\alpha(b) = u$ (actually we should define $\alpha(t)$ in an open set containing $[a, b]$). Since $\alpha(t) \in U'_q \cap S$

By shrinking V_q further, we may assume that $V_q = U'_q \times I$ where $U'_q \subseteq U_q$, $I \subseteq \mathbb{R}$, $0 \in I$, $\psi_q(q) \in U'_q$, U'_q open, I open, U'_q connected

and $0 \in I$, we have $\beta(t) \stackrel{\text{def}}{=} \psi_q(\alpha(t), c) \in U'_q \cap S$. So $\beta(b) = u$ is connected to $\beta(a) = q$ through a ^{continuous} curve on S , so $u \in \tilde{S}$. In other words, for $\forall q \in \tilde{S}$, there is an open set W_q about q , s.t. $W_q \cap S \subseteq \tilde{S}$.

Now we define $U = \bigcup_{q \in \tilde{S}} W_q$ which is open, then $\tilde{S} \subseteq U$ by definition.
 ① $\forall x \in \tilde{S}$, we have $x \in U$, $f(x) = c$. So $x \in \{x \in U \mid f(x) = c\}$, so $\tilde{S} \subseteq \{x \in U \mid f(x) = c\}$
 ② $\forall x \in \{x \in U \mid f(x) = c\}$, there must be a $q \in \tilde{S}$, s.t. $x \in W_q$. As $x \in S$, so $x \in W_q \cap S \subseteq \tilde{S}$. Thus, $\{x \in U \mid f(x) = c\} \subseteq \tilde{S}$.

Hence $\tilde{S} = \{x \in U \mid f(x) = c\}$, i.e. \tilde{S} is a surface.

15.14 Suppose $\alpha(t_1) = \alpha(t_2)$ for some $t_1 \neq t_2 \in I$. ^{As} the maximal integral curve of X through $\alpha(t_1)$ is ~~unique~~ ^{unique} denoted as $\beta(t)$ and $\beta(0) = \alpha(t_1)$, then $\alpha(t) = \beta(t - t_1)$ and $\alpha(t) = \beta(t - t_2)$ for all $t \in I$. Setting $\tau = t_2 - t_1$, we have $\alpha(t) = \beta(t - t_1) = \beta(t + \tau - t_2) = \alpha(t + \tau)$ for all t such that both t and $t + \tau \in I$. Thus if α is not one to one then it is periodic. ~~is~~ ^{is} constrained in C . To prove that the maximal integral curve X through $\alpha(t_1)$ is ~~unique~~ ^{unique}, we notice

that first the restriction of X to C is a tangent vector field on C , because $X \cdot \nabla f_i = (\nabla f_1 \times \nabla f_2) \cdot \nabla f_i$ for $i=1,2$.
 So $(f_i \circ \alpha)'(t) = \nabla f_i(\alpha(t)) \cdot \alpha'(t) = \nabla f_i(\alpha(t)) \cdot X(\alpha(t)) = 0$. So $f_i \circ \alpha$ is constant, thus $\alpha(t) \in C$.

To make a map I onto C , ~~first of all~~, C ~~must be~~ ^{is} connected. The proof is similar to the Thm 1 in Chapter 11, except the construction of rectangle B , we now construct

$A = \{ p_0 + s_1 v_1 + s_2 v_2 + r u \mid |s_i| < \varepsilon_i, |r| < \varepsilon_3 \}$ where $v_i = \nabla f_i(p_0)$, $u = X(p_0)$. The $\varepsilon_1, \varepsilon_2, \varepsilon_3$ are chosen as follows. First, so that $J\vec{f}(p)$ is fully ranked for all $p \in A$. This is possible because $J\vec{f}(p_0)$ is fully ranked. Denote $g_r(s_1, s_2) = \vec{f}(p_0 + s_1 v_1 + s_2 v_2 + r u)$, then

$Jg_r = \begin{pmatrix} \nabla f_1 \\ \nabla f_2 \end{pmatrix} (v_1, v_2) = \begin{pmatrix} \nabla f_1 \\ \nabla f_2 \end{pmatrix} (\nabla f_1, \nabla f_2)$. As $\text{rank}(P'P) = \text{rank}(P) = \text{rank}(P')$, $\text{rank} \begin{pmatrix} \nabla f_1 \\ \nabla f_2 \end{pmatrix}_p = 2$ for $\forall p \in A$. So Jg_r is fully ranked for all $p \in A$. Applying Inverse Function Thm, if r is chosen such that $\exists s_1, s_2$ s.t. $\vec{f}(p_0 + s_1 v_1 + s_2 v_2 + r u) = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$, then such s_1, s_2 are unique.

Now let $\gamma(t) = p_0 + h_0(t)u + h_1(t)v_1 + h_2(t)v_2$, where $h_0(t) = (v(t) - p_0) \cdot u / \|u\|^2$.

$h_i(t) = (v(t) - p_0) \cdot v_i / \|v_i\|^2$ ($i=1,2$). h_1, h_2, h_0 are all smooth and $h_i(0) = h_2(0) = h_0(0) = 0$.

$h_0'(0) = \dot{\gamma}(0) \cdot u / \|u\|^2 = 1$ by definition that $\dot{\gamma}(0) = X(p_0) = u$. So we can choose $t_1 < 0 < t_2$

(small enough), s.t. $h_0'(t) > 0$, set $r_1 = h_0(t_1)$, $r_2 = h_0(t_2)$, then for $\forall r \in (r_1, r_2)$, $\exists t \in (t_1, t_2)$, s.t. $h_0(t) = r$.

Now construct $B = \{ p_0 + r u + s_1 v_1 + s_2 v_2 \mid r_1 < r < r_2, |s_i| < \varepsilon_i \}$ ($i=1,2$).

$\forall p_0 + r u + s_1 v_1 + s_2 v_2 \in B \cap C$, then it's belonging to $B \Rightarrow \exists t \in (t_1, t_2)$, $h_0(t) = r$.

Its belonging to $C \Rightarrow \exists s_1, s_2$ s.t. $p_0 + r u + s_1 v_1 + s_2 v_2 \in C$. Now that we know

$p_0 + h_0(t)u + h_1(t)v_1 + h_2(t)v_2 \in C$, so $\Rightarrow s_1 = h_1(t)$, $s_2 = h_2(t)$. So $p_0 + r u + s_1 v_1 + s_2 v_2 \in C$.

i.e. $C \cap B \subseteq C$.