

Second. $\frac{\partial}{\partial x_i} \frac{1}{\|\nabla f\|} \Big|_p = \frac{\partial}{\partial x_i} \left[\sum_{k=1}^{n+1} \left(\frac{\partial f}{\partial x_k} \right)^2 \right]^{-\frac{1}{2}} \Big|_p = \left[\sum_{k=1}^{n+1} \left(\frac{\partial f}{\partial x_k} \right)^2 \right]^{-\frac{3}{2}} \cdot \frac{1}{2} \cdot \sum_{k=1}^{n+1} 2 \frac{\partial f}{\partial x_k} \frac{\partial^2 f}{\partial x_k \partial x_i} \Big|_p$. But $\frac{\partial f}{\partial x_k} \Big|_p = \begin{cases} 0 & k=1, \dots, n \\ \|\nabla f\| & k=n+1 \end{cases}$

$= -\|\nabla f\|^{-3} \cdot \|\nabla f\| \frac{\partial^2 f}{\partial x_{n+1} \partial x_i} = -\|\nabla f\|^{-2} \frac{\partial^2 f}{\partial x_{n+1} \partial x_i}$ So L_p is symmetric

So $\nabla N_{n+1}(p) \cdot e_i = -\|\nabla f\|^{-2} \frac{\partial^2 f}{\partial x_{n+1} \partial x_i} \|\nabla f\| + \|\nabla f\|^{-1} \frac{\partial^2 f}{\partial x_{n+1} \partial x_i} = 0$.

9.12(a) Suppose a parametrized curve $\alpha: I \rightarrow S$. $\alpha(t_0) = p$. $\dot{\alpha}(t_0) = X(\alpha(t_0))$

$\nabla_{X(p)} Y = Y \circ \dot{\alpha}$, $\nabla_{X(p)} Y \cdot N(p) = Y \circ \dot{\alpha} \cdot N \circ \alpha$

But as Y is tangent to S , $(Y \circ \dot{\alpha}) \cdot (N \circ \alpha) = 0 \Rightarrow (Y \circ \dot{\alpha}) \cdot (N \circ \alpha) + (Y \circ \dot{\alpha}) \cdot (N \circ \alpha) = 0$

So $\nabla_{X(p)} Y \cdot N(p) = - (Y \circ \dot{\alpha}) \cdot (N \circ \alpha) \Big|_{t_0} = -Y(p) \cdot L_p(X(p))$

Similarly, one can prove $\nabla_{Y(p)} X \cdot N(p) = -X(p) \cdot L_p(Y(p))$

By Thm 2 (pg 55) $L_p(X(p)) \cdot Y(p) = X(p) \cdot L_p(Y(p))$ Thus $\nabla_{X(p)} Y \cdot N(p) = \nabla_{Y(p)} X \cdot N(p)$

(b) by (a) obvious

9.13. For $\forall v$, define a parametrized curve $\alpha: I \rightarrow U$, $\alpha(t_0) = p$, $\dot{\alpha}(t_0) = v$. For $\forall \epsilon$, there exists a δ s.t. $\|X(p+v) - X(p) - X'(p)(v)\| / \|v\| < \epsilon$, $\forall \|v\| < \delta$. As α is continuous, there exists $\delta_1 > 0$ s.t. $\forall t \in (t_0 - \delta_1, t_0 + \delta_1)$: $\|\alpha(t) - \alpha(t_0)\| < \delta$. Thus

$\|X(p + \alpha(t) - \alpha(t_0)) - X(p) - X'(p)(\alpha(t) - \alpha(t_0))\| / \|\alpha(t) - \alpha(t_0)\| < \epsilon$

i.e. $\|X(\alpha(t)) - X(\alpha(t_0)) - X'(p)(\alpha(t) - \alpha(t_0))\| / \|\alpha(t) - \alpha(t_0)\| < \epsilon$

i.e. $\lim_{t \rightarrow t_0} \frac{\|X(\alpha(t)) - X(\alpha(t_0)) - X'(p)(\alpha(t) - \alpha(t_0))\|}{\|\alpha(t) - \alpha(t_0)\|} = 0$ (*)

Notice $\lim_{t \rightarrow t_0} \frac{\alpha(t) - \alpha(t_0)}{t - t_0} = \dot{\alpha}(t_0) = v$ So $\lim_{t \rightarrow t_0} \frac{\|\alpha(t) - \alpha(t_0)\|}{|t - t_0|} = \|v\|$ (1)

$\lim_{t \rightarrow t_0} \frac{X(\alpha(t)) - X(\alpha(t_0))}{t - t_0} = \nabla_v X$ (by definition of $\nabla_v X$) (2)

As $X'(p)$ is a linear map, suppose its corresponding matrix is A , thus

If $\lim_{v \rightarrow v} v = v$ then $\lim_{v \rightarrow v} A(v) = A(v)$ $\lim_{t \rightarrow t_0} \frac{X'(p)(\alpha(t) - \alpha(t_0))}{t - t_0} = \lim_{t \rightarrow t_0} X'(p) \left(\frac{\alpha(t) - \alpha(t_0)}{t - t_0} \right)$ (since $X'(p)$ is linear)

use basis expression must finite dimensional $= X'(p) \left(\lim_{t \rightarrow t_0} \frac{\alpha(t) - \alpha(t_0)}{t - t_0} \right) = X'(p)(v)$ (3)

Plugging (1) (2) (3) into (*) $\|\nabla_v X - X'(p)(v)\| / \|v\| = 0$ i.e. $\nabla_v X = X'(p)(v)$

9.14 $L_p(p, v) \stackrel{\text{def of } L_p}{=} -\nabla_v N(p) \stackrel{\text{def of } \tilde{N}}{=} -\nabla_v \tilde{N}(p) \stackrel{\text{result of 9.13}}{=} -\tilde{N}'(p)(v)$

9.15 (a) $\ddot{\alpha}(t) = X(\ddot{\alpha}(t)) \Leftrightarrow \begin{cases} \dot{x}_1 = u_1, \dots, \dot{x}_{n+1} = u_{n+1} \\ \ddot{u}_k = - (u_1, \dots, u_{n+1}) \cdot \left(\sum_{i=1}^{n+1} u_i \frac{\partial N_i}{\partial x_i}, \dots, \sum_{i=1}^{n+1} u_i \frac{\partial N_{n+1}}{\partial x_i} \right) N_k = -N_k \sum_{i,j=1}^{n+1} u_i u_j \frac{\partial N_j}{\partial x_i} \end{cases}$ (denote $\alpha = (x_1, \dots, x_{n+1})$, $\ddot{\alpha} = (\alpha, u_1, \dots, u_{n+1})$)

So $\ddot{x}_k + N_k \cdot \sum_{i,j=1}^{n+1} \dot{x}_i \dot{x}_j \frac{\partial N_j}{\partial x_i} = 0$ which is the same as (6) f N_k .

Then follow the proof in the theorem of chapter 7, α is a geodesic of S . ($\alpha \in S$ is assumed)

Note the equation $\ddot{\alpha}(t) = X(\ddot{\alpha}(t))$ is 1st order differential system in U and X so unique solution

(b) $X(\beta(t)) = \beta(t) \Leftrightarrow \begin{cases} \dot{\beta}_1 = \beta_2 \\ \dot{\beta}_2 = -(\beta_2 \cdot \nabla_{\beta_2} N) N(\beta_1) \end{cases}$ As in (a), we can