

11.14 If C is connected, then there is a one-to-one ^{global} parametrization $\alpha(t): [a,b] \rightarrow C$.
 $\int_C \omega_X = \int_a^b X(\alpha(t)) \cdot \dot{\alpha}(t) dt = \int_a^b \|\dot{\alpha}(t)\| dt = l(C)$ (as X is rotating $\omega/\|\omega\|$ by $-\pi/2$)
 If C is not connected, then the above is true for each segment, so globally holds too

11.15 Treat α as $\tilde{\alpha}$, then $\alpha(t) = (\cos \theta(t), \sin \theta(t))$ by proof in Thm 3 ($\theta(t) \equiv \theta_0 + \int_{t_0}^t \eta(\tilde{\alpha}(t)) dt$)
 As for uniqueness: If $\theta_1(t)$ and $\theta_2(t)$ satisfy: $\cos \theta_1(t) \equiv \cos \theta_2(t)$, $\sin \theta_1(t) \equiv \sin \theta_2(t)$
 $\theta_1(t_0) = \theta_2(t_0) = \theta_0$, then $\theta_1(t) = \theta_2(t)$ for all $t \in I$. Proof: By first two equations
 $\sin(\theta_1(t) - \theta_2(t)) = 0$ so $\cos(\theta_1(t) - \theta_2(t)) \cdot (\dot{\theta}_1(t) - \dot{\theta}_2(t)) = 0$.
 But $\sin(\theta_1 - \theta_2) = 0 \Rightarrow \cos(\theta_1 - \theta_2) \neq 0$, so $\dot{\theta}_1(t) - \dot{\theta}_2(t) = 0$ so $\theta_1(t) \equiv \theta_2(t)$ as it holds $\stackrel{t=0}{\text{for}}$

11.16 Let $\beta(t) = f(t) \cdot \alpha(t)$. Define $\varphi_1(t) = \varphi_1(a) + \int_a^t \eta$, $\varphi_2(t) = \varphi_2(a) + \int_a^t \eta$
 $\varphi_1(a)$ is chosen so that $\alpha(a)/\|\alpha(a)\| = (\cos \varphi_1(a), \sin \varphi_1(a))$ and $\varphi_1(a) \in [0, 2\pi)$
 $\varphi_2(a) \dots \dots \dots \beta(a)/\|\beta(a)\| = (\cos \varphi_2(a), \sin \varphi_2(a))$ and $\varphi_2(a) \in [0, 2\pi)$
 As $\beta(a)/\|\beta(a)\| = \alpha(a)/\|\alpha(a)\|$ ^{since $f > 0$} and such choice of $\varphi_1, \varphi_2(a)$ is unique, we have
 $\varphi_1(a) = \varphi_2(a)$. Furthermore, by proof in Thm 3,
 $\alpha(t)/\|\alpha(t)\| = (\cos \varphi_1(t), \sin \varphi_1(t))$, $\beta(t)/\|\beta(t)\| = (\cos \varphi_2(t), \sin \varphi_2(t))$
 As $\alpha(t)/\|\alpha(t)\| \equiv \beta(t)/\|\beta(t)\|$, $\cos \varphi_1(t) \equiv \cos \varphi_2(t)$, $\sin \varphi_1(t) \equiv \sin \varphi_2(t)$
 and $\varphi_1(a) = \varphi_2(a)$. Same as the proof of uniqueness in Ex 11.15 we have
 $\varphi_1(t) \equiv \varphi_2(t)$, $k(\alpha) = \frac{1}{2\pi}(\varphi_1(b) - \varphi_1(a)) = \frac{1}{2\pi}(\varphi_2(b) - \varphi_2(a)) = k(\beta)$. Now may need piece-
 Let $f = \|\alpha\|^{-1}$ (As $\|\alpha\| \neq 0$), then $k(\alpha) = k(\alpha/\|\alpha\|)$. wise, but still true
 Actually no need of α being closed and $f(a) = f(b)$. $\int \alpha \eta \equiv \int \beta \eta$.

11.17 Since by Ex 11.16, α and $\alpha/\|\alpha\|$ have the same winding number, it is now equivalent to
 proving that with $\varphi(t, u)$ redefined as $\hat{\varphi}(t, u) = \varphi(t, u)/\|\varphi(t, u)\|$, the result holds. Now $\|\hat{\varphi}(t, u)\| = 1$
 for all u , and t , and $\varphi(t, u)/\|\varphi(t, u)\|$ is continuous as $\|\varphi(t, u)\|$ is continuous.
 and $\hat{\varphi}_u(t)$ is smooth on each $[t_i, t_{i+1}]$, $\hat{\varphi}_u(a) = \hat{\varphi}_u(b)$.

As $[a, b] \times [0, 1]$ is compact, and $\hat{\varphi}$ is continuous, $\hat{\varphi}$ must be uniform continuous, i.e.
 $\forall \varepsilon_1, \exists \delta_1, \forall (t_1, u_1), (t_2, u_2) \text{ with } \| (t_1, u_1) - (t_2, u_2) \| < \delta_1, \|\hat{\varphi}(t_1, u_1) - \hat{\varphi}(t_2, u_2)\| < \varepsilon_1$. Specifically, let $t_1 = t_2$
 $\|\hat{\varphi}(t, u_1) - \hat{\varphi}(t, u_2)\| < \varepsilon_1$, i.e. $\hat{\varphi}(t, u_1) \cdot \hat{\varphi}(t, u_2) \geq 1 - \frac{\varepsilon_1^2}{2} = 1 - \varepsilon_2$ ($\varepsilon_2 \equiv \frac{\varepsilon_1^2}{2}$) $\forall |u_1 - u_2| < \varepsilon_1$.
 Define $\theta_u(t) = \theta_u(a) + \int_a^t \hat{\varphi}_u \eta$, $\theta_x(t) = \theta_x(a) + \int_a^t \hat{\varphi}_x \eta$. $\forall u \in [0, 1]$, $x \in (u - \varepsilon_1, u + \varepsilon_1) \cap [0, 1]$
 $\theta_u(a)$ is chosen so that $\hat{\varphi}_u(a) = (\cos \theta_u(a), \sin \theta_u(a))$. Likewise, $\hat{\varphi}_x(a) = (\cos \theta_x(a), \sin \theta_x(a))$
 and $\theta_u(a), \theta_x(a) \in [0, 2\pi)$. For $\forall t$, by proof in Thm 3,
 $\hat{\varphi}_u(t) = (\cos \theta_u(t), \sin \theta_u(t))$, $\hat{\varphi}_x(t) = (\cos \theta_x(t), \sin \theta_x(t))$