

Obviously, φ is continuous. $\varphi(t, c) = \alpha(t) \cdot p$. $\varphi(t, d) = \alpha(t) \cdot q$
 $k(\varphi(t, c)) = k(\varphi(t, d)) \Rightarrow k_p(\alpha) = k_q(\alpha)$ (as $k_p(\alpha) = k(\alpha(t) \cdot p)$)

12.1 The matrix corresponding to L_p is $A = \|g\|^{-3} (g \cdot g^T - \|g\|^2 I)$ (H is the Hessian) $g = \nabla f$
 ~~$k(p)$~~ $L_p(v) = -\|g\|^{-1} H \cdot v$, $k(v) = -\|g\|^{-1} v^T H v = \varphi_p(v)$ for $v \in S_p$.

12.2 $\nabla f = (1, 1, \dots, 1)$, $v_i = \frac{1}{\sqrt{2}}(1, 0, \dots, 0, -1, 0, \dots, 0)$ where \pm is the i^{th} spot after 1, $i = 1, \dots, n$.
 $\nabla f = \sqrt{n+1}$, $\frac{\partial^2 f}{\partial x_i \partial x_j} = 0$. So $k(v) = \varphi_p(v) = 0 \forall v$ by Ex 12.1. So any $v \in S_p$ $\|v\|=1$
 is a principal curvature direction, with principal curvature 0.
 $k(p) = 0$ $H(p) = 0$.

12.3 $\nabla f = (2x_1, \dots, 2x_{n+1})$ $\|\nabla f(p)\| = 2r$ $H = 2 \cdot I$ $k(v) = \frac{1}{r} v^T v$.
 Any $v \in S_p$, $\|v\|=1$ is a principal curvature direction, with principal curvature $\frac{1}{r}$.
 $k(p) = (-r)^{-n}$, $H(p) = \frac{1}{r}$

12.4 $\nabla f = (\frac{2x_1}{a^2}, \frac{2x_2}{b^2}, \frac{2x_3}{c^2})$ $H = \begin{pmatrix} \frac{2a^{-2}}{0} & 0 & 0 \\ 0 & \frac{2b^{-2}}{0} & 0 \\ 0 & 0 & \frac{2c^{-2}}{0} \end{pmatrix}$ ~~$k(p)$~~ $\|\nabla f(p)\| = \frac{2}{a}$ $\nabla f(p) = (\frac{2}{a}, 0, 0)$
 $k(v) = -\frac{a}{2} (\frac{2}{a^2} v_1^2 + \frac{2}{b^2} v_2^2 + \frac{2}{c^2} v_3^2) = -a (\frac{v_1^2}{a^2} + \frac{v_2^2}{b^2} + \frac{v_3^2}{c^2})$ $\forall v \in S_p$, $v = (0, v_2, v_3)$
 $v_2^2 + v_3^2 = 1$, So $k(v)$ attains its extremum at $(0, \pm 1, 0)$ and $(0, 0, \pm 1)$ i.e. principal
 curvature directions, corresponding to principal curvature $\frac{-a}{b^2}$ and $\frac{-a}{c^2}$ respectively.
 $k(p) = \frac{a^2}{b^2 c^2}$, $H(p) = \frac{-a}{2} (\frac{1}{b^2} + \frac{1}{c^2})$

12.5 $\nabla f = (\frac{2x_1}{a^2}, \frac{2x_2}{b^2}, -\frac{2x_3}{c^2})$ $H = 2 \begin{pmatrix} \frac{1}{a^2} & 0 & 0 \\ 0 & \frac{1}{b^2} & 0 \\ 0 & 0 & -\frac{1}{c^2} \end{pmatrix}$ $\|\nabla f(p)\| = \frac{2}{a}$ $\nabla f(p) = (\frac{2}{a}, 0, 0)$
 $k(v) = -\frac{a}{2} (\frac{2}{a^2} v_1^2 + \frac{2}{b^2} v_2^2 - \frac{2}{c^2} v_3^2) \forall v \in S_p$, $v = (0, v_2, v_3)$ $v_2^2 + v_3^2 = 1$. So
 $k(v) = -\frac{a}{2} (\frac{2}{b^2} v_2^2 - \frac{2}{c^2} v_3^2) = -a (\frac{1}{b^2} (1 - v_3^2) - \frac{1}{c^2} v_3^2) = a [\frac{1}{b^2} + \frac{1}{c^2} v_3^2 - \frac{1}{b^2}]$ $v_3^2 \in [0, 1]$
 $k(v)$ attains max when $v_3^2 = 1$, $\max = \frac{a}{c^2}$, attains min when $v_3^2 = 0$ $\min = \frac{-a}{b^2}$
 So principal curvature and principal curvature directions are: $(0, 0, \pm 1), \frac{a}{c^2}$, $(0, \pm 1, 0), \frac{-a}{b^2}$
 $k(p) = -\frac{a^2}{b^2 c^2}$, $H(p) = \frac{a}{2} (\frac{1}{c^2} - \frac{1}{b^2})$

12.6 $\nabla f = (2x_1, 2x_2 (1 - 2(x_2^2 + x_3^2))^{-1/2}, 2x_3 (1 - 2(x_2^2 + x_3^2))^{-1/2})$
 $H = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 - 4x_3^2 (x_2^2 + x_3^2)^{-3/2} & 4x_2 x_3 (x_2^2 + x_3^2)^{-3/2} \\ 0 & 4x_2 x_3 (x_2^2 + x_3^2)^{-3/2} & 2 - 4x_2^2 (x_2^2 + x_3^2)^{-3/2} \end{pmatrix}$ For (a) $\nabla f(p) = (0, 2, 0)$ $\|\nabla f\| = 2$, $(p = (0, 3, 0))$
 $H = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2/3 \end{pmatrix}$
 (b) $p = (0, 1, 0)$, $\nabla f(p) = (0, -2, 0)$ $\|\nabla f\| = 2$
 $H = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -2 \end{pmatrix}$