

by plugging into (1), (2)

So $\frac{\partial \tilde{N}_i}{\partial x_j}|_{ap} = \frac{1}{a} \frac{\partial \tilde{N}_i}{\partial x_j}|_p$ So $\tilde{k}(v) = \frac{k(v)}{a}$, which is true at all (shared) stationary points.

But mean curvature H is the average of k at stationary points, thus $H(ap) = \frac{1}{a} H(p)$.

(d) K (Gauss-Kronecker curvature) is the product of $k(v)$ at stationary points

$$so \quad K(ap) = a^{-n} k(p)$$

Remark: Above argument based on stationary points is not strict enough, especially considering the multiplicity of L_p 's eigenvalues. A better proof is: $\forall v, w \in S_p$. As $\nabla g(ap) = \frac{1}{a} \nabla f(p)$

$$so \quad S_p = \mathcal{L}_{ap}. \quad \forall v, w \in S_p. \quad L_p(v) \cdot w = \frac{1}{2}[k(v+w) - k(v) - k(w)] \quad \text{as } \tilde{k}(v) = k(v)/a$$

let \tilde{L}_p be Weingarten map on S at $ap \rightarrow \tilde{L}_p(v) \cdot w = \frac{1}{2}[\tilde{k}(v+w) - \tilde{k}(v) - \tilde{k}(w)] = \frac{1}{a} L_p(v) \cdot w$

Since w is arbitrary in S_p , so $\tilde{L}_p(v) = \frac{1}{a} L_p(v)$, so each eigenvalue λ_i of \tilde{L}_p corresponds to the eigenvalue λ_i/a of L_p . As H and K are average/product of eigenvalues, we have

$$H(ap) = \frac{1}{a} H(p) \quad k(ap) = a^{-n} k(p) \quad \text{if } \# \text{ eigenvalues of } \tilde{L}_p \text{ is even, set } w = \tilde{L}_p(v) - \frac{1}{a} L_p(v) \in S_p$$

$$\text{then one has } (\tilde{L}_p(v) - \frac{1}{a} L_p(v)) \cdot (\tilde{L}_p(v) - \frac{1}{a} L_p(v)) = 0. \text{ so } \tilde{L}_p(v) = \frac{1}{a} L_p(v)$$

13.1 If S is convex at p , then h_u ($u = N(p)$ Gauss map) attains local max/min at p .

so \mathcal{Q}_p is semi-definite, so $\mathcal{Q}_p = \pm \mathcal{D}_p$ is also semi-definite. But the Gauss-Kronecker curvature, which is equal to the product of all eigenvalues of \mathcal{Q}_p , is negative.

As S_p is even dimensional, there must be one positive and one negative eigenvalue, which contradicts the fact that \mathcal{Q}_p is semi-definite. So S is not convex at p .

13.2 $\forall v, w \in S_p. \quad \nabla_v(\text{grad } h) w = \nabla_v(\nabla h - (\nabla h \cdot N)N) w = \nabla_v(\nabla h) w - (\nabla h \cdot N)(\nabla_v N \cdot w)$

$$\nabla_w(\text{grad } h) v = \nabla_w(\nabla h - (\nabla h \cdot N)N) v = \nabla_w(\nabla h) v - (\nabla h \cdot N)(\nabla_w N \cdot v)$$

We know L_p is self-adjoint, i.e., $\nabla_v N \cdot w = \nabla_w N \cdot v$. Besides,

$$\nabla_v(\nabla h) w = v^T H w = w^T H v = \nabla_w(\nabla h) v \quad \text{so } \nabla_v(\text{grad } h) w = \nabla_w(\text{grad } h) v, \text{ so self-adjoint}$$

13.3. (a) \Rightarrow If \mathcal{Q} is posDef, then \forall eigenvector v , $\mathcal{Q}(v) = \lambda v$, $\mathcal{Q}(v) \cdot v = \lambda > 0$ as \mathcal{Q} is PosDef

\Leftarrow We know that the eigenvectors v_1, \dots, v_n make up an orthonormal basis on S_p . $\forall v \in S_p$.

$$\text{Let } v = \sum_{i=1}^n a_i v_i. \quad \mathcal{Q}(v) \cdot v = \mathcal{Q}\left(\sum_{i=1}^n a_i v_i\right) \cdot \sum_{i=1}^n a_i v_i = \left(\sum_{i=1}^n a_i \mathcal{Q}(v_i)\right) \cdot \left(\sum_{i=1}^n a_i v_i\right) = \left(\sum_{i=1}^n a_i \lambda_i v_i\right) \cdot \left(\sum_{i=1}^n a_i v_i\right) = \sum_{i=1}^n a_i^2 \lambda_i \geq 0 \text{ because } \lambda_i \geq 0$$

\Leftarrow It is equal to 0 iff ~~$a_i = 0$~~ $a_i = 0$, i.e. $v = 0$.

(b) \Leftarrow Since \mathcal{L} is self-adjoint linear transformation, its associated matrix \mathcal{L} is symmetric. so it has two real valued eigenvalues λ_1, λ_2 . $\det \mathcal{L} > 0 \Rightarrow \lambda_1, \lambda_2 > 0$. But if $\lambda_1 < 0, \lambda_2 < 0$, then \mathcal{L} is negative definition, i.e., there can't be any v : $\mathcal{L}(v) > 0$. thus $\lambda_1 > 0, \lambda_2 > 0$.