

22.1 Example 1: $\|\psi(p) - \psi(q)\| = \|(p+a) - (q+a)\| = \|p-q\|$

Example 2: $\|\psi(p) - \psi(q)\| = \|(Ap - Aq)\| = \|A(p-q)\| = \|p-q\|$, $A = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$. $\|A(x_1, x_2)\| =$

$$\|(c\cos\theta x_1 - s\sin\theta x_2, s\sin\theta x_1 + c\cos\theta x_2)\| = \sqrt{(c\cos\theta x_1 - s\sin\theta x_2)^2 + (s\sin\theta x_1 + c\cos\theta x_2)^2} = \sqrt{x_1^2 + x_2^2} = \sqrt{x_1^2 + x_2^2}$$

Example 3: $\|\psi(p) - \psi(q)\| = \|p + 2(b-p-a) \cdot a - q - 2(b-q-a) \cdot a\| = \|p-q - 2((p-q) \cdot a)\|$, $b+p-q =$
 $= \left[(x_2(x \cdot a) \cdot a)^T (x_2(x \cdot a) \cdot a) \right]^{1/2} = [x^T x + 4(x \cdot a)^2 - 4(x \cdot a)^2]^{1/2} = \|x\| = \|p-q\|$.

22.2. If $x \in \mathbb{R}^{n+1}$, $\psi_i(\psi_j(x)) = \psi_i(x+a) \stackrel{\psi_i \text{ is linear}}{=} \psi_i(x) + \psi_i(a) = \tilde{\psi}_j(\psi_i(x))$, $\tilde{\psi}_2(\tilde{x}) = \tilde{x} + \psi_1(a)$.

22.3 (a) $\psi(v) \cdot \psi(w) = v \cdot w \Rightarrow \psi(v) \cdot \psi(v) = v \cdot v \Rightarrow \|\psi(v)\| = \|v\|$.

$$\|\psi(v)\| = \|v\| \Rightarrow \psi(v) \cdot \psi(w) = \frac{1}{2} [\|\psi(v+w)\|^2 - \|\psi(v)\|^2 - \|\psi(w)\|^2] = \\ = \frac{1}{2} [\|v+w\|^2 - \|v\|^2 - \|w\|^2] = v \cdot w$$

(b) If orthonormal basis $\{e_1, \dots, e_n\}$, let $v = \sum_{i=1}^n v_i e_i$, then if $\{\psi(e_1), \dots, \psi(e_{n+1})\}$ is orthonormal we have $\|\psi(v)\| = \|\psi(\sum_{i=1}^n v_i e_i)\| = \left\| \sum_{i=1}^n v_i \psi(e_i) \right\| = \sqrt{\sum_{i=1}^n v_i^2} = \|v\|$

By (a), if $\{e_1, \dots, e_n\}$ is orthonormal, then $\psi(e_i) \cdot \psi(e_j) = e_i \cdot e_j = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$
 so $\{\psi(e_1), \dots, \psi(e_{n+1})\}$ is orthonormal basis for \mathbb{R}^{n+1}

(c) Let $\psi(e_i) = \sum_{j=1}^n a_{ij} e_j$, where $\{e_1, \dots, e_n\}$ is an orthonormal basis of \mathbb{R}^{n+1} .

① If A is orthogonal, then letting $P = \{\psi(e_1), \dots, \psi(e_n)\} = AQ$ where $Q = \{e_1, \dots, e_n\}$, we have $P^T P = Q^T A^T A Q = Q^T Q = I$, so $\{\psi(e_1), \dots, \psi(e_n)\}$ is orthonormal

By (b) we have ψ is orthogonal transformation.

② If ψ is orthogonal, then by (b) $P = \{\psi(e_1), \dots, \psi(e_n)\}$ is also orthonormal
 $I = P^T P = A Q Q^T A^T = A A^T$ so A is orthogonal.

22.4 (a) By Ex 22.3 (c). The matrix is orthonormal \Leftrightarrow orthogonal linear transformation

So rotation $\Leftrightarrow \begin{vmatrix} x_1 & x_3 \\ x_2 & x_4 \end{vmatrix} = 1$ and $A^T A = I$ where $A = \begin{pmatrix} x_1 & x_2 \\ x_3 & x_4 \end{pmatrix}$

$$\Leftrightarrow x_1^2 + x_3^2 = 1, x_1 x_2 + x_3 x_4 = 0, x_2^2 + x_4^2 = 1, x_1 x_4 - x_2 x_3 = 0 \quad (*)$$

Let $x_1 = \cos\theta, x_3 = \sin\theta, x_2 = \cos\varphi, x_4 = \sin\varphi$, we have.

$$\cos(\theta + \varphi) = \cos\theta \cos\varphi - \sin\theta \sin\varphi = x_1 x_2 + x_3 x_4 = 0$$

$$\sin(\theta + \varphi) = \sin\theta \cos\varphi + \cos\theta \sin\varphi = -x_3 x_2 + x_1 x_4 = 0$$

$$\text{So } \theta + \varphi = 2k\pi + \frac{\pi}{2}, \sin\varphi = \cos\theta, \cos\varphi = \sin\theta, \text{ so } A = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

Obviously, A in such a form must satisfy (*).

(b) If eigenvalue and eigenvector λ_i, x_i : $\psi x_i = \lambda_i x_i$, then $x_i^T \psi^T \psi x_i = x_i^T \lambda_i^2 x_i$

As $\psi^T \psi = I$ by Ex 22.3 (c), $1 = x_i^T \cdot x_i = \lambda_i^2$. So $\lambda_i = \pm 1$. If all λ_i are -1 then $|\psi| = \prod_{i=1}^n \lambda_i = -1$, violating definition of rotation. So $\exists \lambda_i: \psi x_i = x_i$.